

# **CS 2336: Discrete Mathematics**

## **Chapter 7**

### **Relations: The Second Time Around**

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# Outline

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**7.1 Relations Revisited: Properties of Relations**

**7.2 Computer Recognition: Zero-One Matrices and Directed Graphs**

**7.3 Partial Orders: Hasse Diagrams**

**7.4 Equivalence Relations and Partitions**

**7.5 Finite State Machines: The Minimization Process**

# Recap

- For sets  $A, B$ , any subset of  $A \times B$  is called a **(binary) relation** from  $A$  to  $B$ . Any subset of  $A \times A$  is called a **(binary) relation** on  $A$ 
  - Ex: Let  $\Sigma$  be an alphabet, with language  $A \subseteq \Sigma^*$ . For  $x, y$  in  $A$ , we define  $x \mathcal{R} y$  if  $x$  is a prefix of  $y$ .
  - Ex: Consider a state machine  $M = (S, \mathcal{I}, \mathcal{O}, \nu, \omega)$ 
    - **First level of reachability**:  $s_1 \mathcal{R} s_2$  if  $\nu(s_1, x) = s_2$
    - **Second level**:  $s_1 \mathcal{R} s_2$  if  $\nu(s_1, x_1 x_2) = s_2, x_1 x_2 \in \mathcal{I}^2$
  - Ex: Define a relation on integers,  $x \mathcal{R} y$  if  $a \leq b$
  - Ex: Define a relation on integer with modulo  $n$

# Reflexive

- A relation  $\mathcal{R}$  on a set  $A$  is called **reflexive** if for all  $x \in A$ ,  $(x, x) \in \mathcal{R}$
- Ex 7.4: Consider  $A = \{1, 2, 3, 4\}$ , a relation  $\mathcal{R} \subseteq A \times A$  is reflexive iff  $\mathcal{R} \supseteq \{(1, 1), (2, 2), (3, 3), (4, 4)\}$ 
  - Are the following relations reflexive?
    - $\mathcal{R}_1 = \{(1, 1), (2, 2), (2, 3)\}$
    - $\mathcal{R}_2 = \{(x, y) \mid x, y \in A, x \geq y\}$



# Symmetric

- A relation  $\mathcal{R}$  on a set  $A$  is called **symmetric** if for all  $x, y \in A$ , we know  $(x, y) \in \mathcal{R} \implies (y, x) \in \mathcal{R}$

- Ex 7.6: Consider  $A = \{1, 2, 3\}$ , are the following relations symmetric or reflexive?

$$\mathcal{R}_1 = \{(1, 2), (2, 1), (1, 3), (3, 1)\}$$

$$\mathcal{R}_2 = \{(1, 1), (2, 2), (2, 3), (3, 3)\}$$

$$\mathcal{R}_3 = \{(1, 1), (2, 2), (2, 3), (3, 3), (3, 2)\}$$

# Transitive

- A relation  $\mathcal{R}$  on a set  $A$  is called **transitive** if for all  $x, y, z \in A$ , we know  $x\mathcal{R}y$  and  $y\mathcal{R}z \implies x\mathcal{R}z$
- Ex 7.10: Consider  $A = \{1, 2, 3, 4\}$ , are the following relations transitive?

$$\mathcal{R}_1 = \{(1, 1), (2, 3), (3, 4), (2, 4)\}$$

$$\mathcal{R}_2 = \{(1, 3), (3, 4)\}$$

# Antisymmetric

- A relation  $\mathcal{R}$  on a set  $A$  is called **antisymmetric** if for all  $a, b \in A$ , if  $a\mathcal{R}b$  and  $b\mathcal{R}a \implies a = b$
- Ex 7.11: For any universe  $\mathcal{U}$ , relation  $\mathcal{R}$  defined on  $\mathcal{P}(\mathcal{U})$  by  $(A, B) \in \mathcal{R}$  if  $A \subseteq B$ . Is this relation antisymmetric? How about reflexive, symmetric, and transitive?

# Partial Order

- A relation  $\mathcal{R}$  on a set  $A$  is called **partial order** if it is reflexive, antisymmetric, and transitive
- Ex 7.14: Are the following relations partial order?
  - Define a relation on  $\mathbb{Z}$  by  $(a, b) \in \mathcal{R}$  if  $a \leq b$
  - Let  $n \in \mathbb{Z}^+$ , for  $x, y \in \mathbb{Z}$ , the modulo  $n$  relation  $\mathcal{R}$  is defined by  $x\mathcal{R}y$ , if  $x - y$  is a multiple of  $n$

# Equivalence Relation

- A relation  $\mathcal{R}$  on a set  $A$  is called **equivalence relation** if it is reflexive, symmetric, and transitive
- Ex 7.16: Are the following relations equivalence relations?

$$\mathcal{R}_1 = \{(1, 1), (2, 2), (3, 3)\}$$

$$\mathcal{R}_2 = \{(1, 1), (2, 2), (2, 3), (3, 2), (3, 3)\}$$

$$\mathcal{R}_3 = \{(1, 1), (1, 3), (2, 3), (3, 1), (3, 3)\}$$

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**7.1 Relations Revisited: Properties of Relations**

**7.2 Computer Recognition: Zero-One Matrices and Directed Graphs**

**7.3 Partial Orders: Hasse Diagrams**

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**7.5 Finite State Machines: The Minimization Process**

# Composite Relation

- If  $\mathcal{R}_1 \subseteq A \times B$  and  $\mathcal{R}_2 \subseteq B \times C$  then the **composite relation**  $\mathcal{R}_1 \circ \mathcal{R}_2$  is a relation from  $A$  to  $C$  defined by

$$\mathcal{R}_1 \circ \mathcal{R}_2 = \{(x, z) \mid x \in A, z \in C, \exists y \in B \text{ s.t. } (x, y) \in \mathcal{R}_1, (y, z) \in \mathcal{R}_2\}$$

- **Ex 7.17:** Let  $A = \{1, 2, 3, 4\}$ ,  $B = \{w, x, y, z\}$ ,  $C = \{5, 6, 7\}$ .  
If  $\mathcal{R}_1 = \{(1, x), (2, x), (3, y), (3, z)\}$  and  $\mathcal{R}_2 = \{(w, 5), (x, 6)\}$ .  
Write  $\mathcal{R}_1 \circ \mathcal{R}_2$ . If  $\mathcal{R}_3 = \{(w, 5), (w, 6)\}$ , what is  $\mathcal{R}_1 \circ \mathcal{R}_3$ ?

# Association and Powers

- Let  $\mathcal{R}_1 \subseteq A \times B, \mathcal{R}_2 \subseteq B \times C, \mathcal{R}_3 \subseteq C \times B$ , we have

$$\mathcal{R}_1 \circ (\mathcal{R}_2 \circ \mathcal{R}_3) = (\mathcal{R}_1 \circ \mathcal{R}_2) \circ \mathcal{R}_3$$

- There is no ambiguity if we write  $\mathcal{R}_1 \circ \mathcal{R}_2 \circ \mathcal{R}_3$

- **Powers** of  $\mathcal{R}$  on  $A$  are recursively defined by: (i)  $\mathcal{R}^1 = \mathcal{R}$  and (ii)  $\mathcal{R}^{n+1} = \mathcal{R} \circ \mathcal{R}^n$ , where  $n \in \mathbb{Z}^+$
- Ex 7.19: If  $A = \{1, 2, 3, 4\}, \mathcal{R} = \{(1, 2), (1, 3), (2, 4), (3, 2)\}$ , what are  $\mathcal{R}^2, \mathcal{R}^3, \mathcal{R}^4$  ?



# Zero-One Matrix

- An  $m$  by  $n$  **zero-one matrix**  $E = (e_{ij})_{m \times n}$ , is a rectangular array with  $m$  rows and  $n$  columns, where each  $e_{ij}$  denotes the entry in the  $i$ th row and  $j$ th column, which can be either  $0$  or  $1$
- Ex 7.20:  $E$  is a 3 by 4 zero-one matrix

$$E = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

# Relation Matrices

- Ex 7.21: Write the following relations into **relation matrices**  $A = \{1, 2, 3, 4\}$ ,  $B = \{w, x, y, z\}$ ,  $C = \{5, 6, 7\}$

$$\mathcal{R}_1 = \{(1, x), (2, x), (3, y), (3, z)\}$$

$$\mathcal{R}_2 = \{(w, 5), (x, 6)\}$$

$$M(\mathcal{R}_1) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad M(\mathcal{R}_2) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$M(\mathcal{R}_1)M(\mathcal{R}_2) = ?$$

- Note that, a convention used here is  $1 + 1 = 1$ , which is called boolean addition

# Some Properties

- Let  $A$  be the set with  $n$  elements.  $\mathcal{R}$  is a relation on  $A$ . If  $M(\mathcal{R})$  is the relation matrix for  $\mathcal{R}$  then
  - $M(\mathcal{R}) = \mathbf{0}$  iff  $\mathcal{R} = \emptyset$
  - $M(\mathcal{R}) = \mathbf{1}$  iff  $\mathcal{R} = A \times A$
  - $M(\mathcal{R}^m) = M(\mathcal{R})^m$ , for  $m \in \mathbb{Z}^+$

# Precedes, Identify Matrix, Transpose

- Let  $E$  and  $F$  be two  $m$  by  $n$   $(0,1)$  matrices. We say  $E$  **precedes**, or is less than  $F$ , and we write  $E \leq F$  if  $e_{ij} \leq f_{ij}, \forall 1 \leq i \leq m, 1 \leq j \leq n$

- **Identify Matrix:**

$$I_n = (\delta_{ij})_{n \times n}, \text{ where } \delta_{ij} = 1 \text{ if } i = j, \delta_{ij} = 0, \text{ o.w.}$$

- **Transpose:**

$$A^{\text{tr}} : a_{ji}^* = a_{ij}$$

# Relations in Matrices

- Given a relation  $\mathcal{R}$  on  $A$ , where  $|A| = n$ . Let  $M$  be the relation matrix of  $\mathcal{R}$ 
  - $\mathcal{R}$  is reflexive iff  $I_n \leq M$
  - $\mathcal{R}$  is symmetric iff  $M = M^{\text{tr}}$
  - $\mathcal{R}$  is transitive iff  $M^2 \leq M$
  - $\mathcal{R}$  is antisymmetric iff  $M \cap M^{\text{tr}} \leq I_n$ 
    - where  $1 \cap 1 = 1, 1 \cap 0 = 0 \cap 1 = 0, 0 \cap 0 = 0$

# Directed Graph

- Let  $V$  be a finite set. A **directed graph** (or **digraph**)  $G$  on  $V$  is made up the elements of  $V$ , called the **vertices** or **nodes** of  $G$ , and a subset  $E$ , of  $V \times V$ , that contains the **directed edges**, or **arcs**, of  $G$ . The set  $V$  is called the **vertex set** of  $G$ , and the set  $E$  is called the **edge set**.  $G = (V, E)$  denotes the graph.
- If  $(a, b) \in E$ , then there is an edge from  $a$  to  $b$ . Vertex  $a$  is called the **origin**, and  $b$  is called **terminus**. We say  $b$  is adjacent from  $a$  and  $a$  is adjacent to  $b$ .
- If  $a \neq b$  then  $(a, b) \neq (b, a)$ . An edge from  $a$  to  $a$  if called a loop.

# Examples of Digraphs

- Are there **isolated vertices**?
- **Undirected edges**  $\{a,b\}=\{b,a\}$

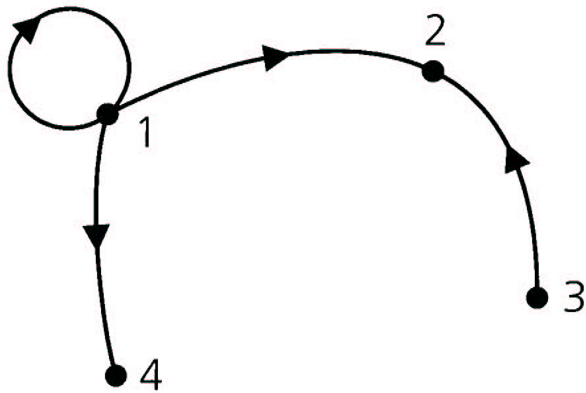


Figure 7.1

●  
5

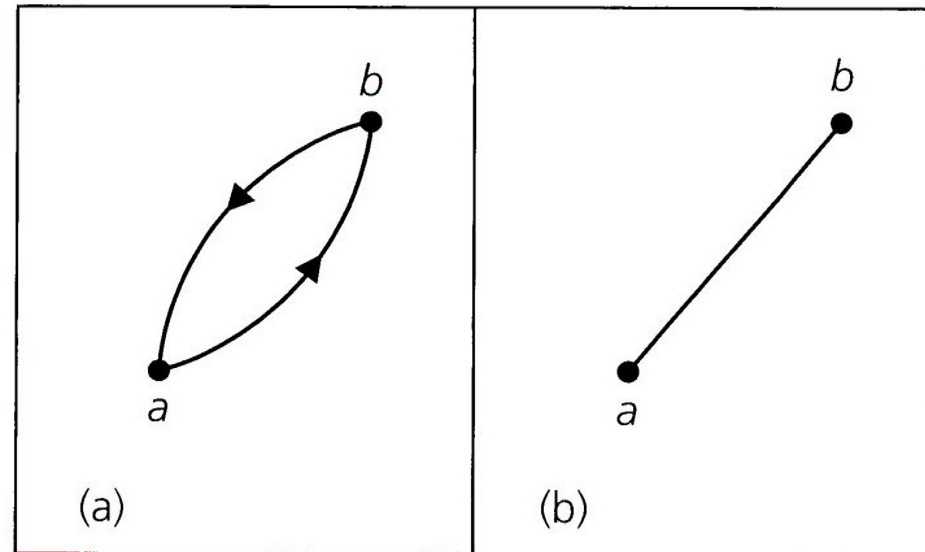


Figure 7.2

# Precedence Graph

- Dependency among statements (computer programs)

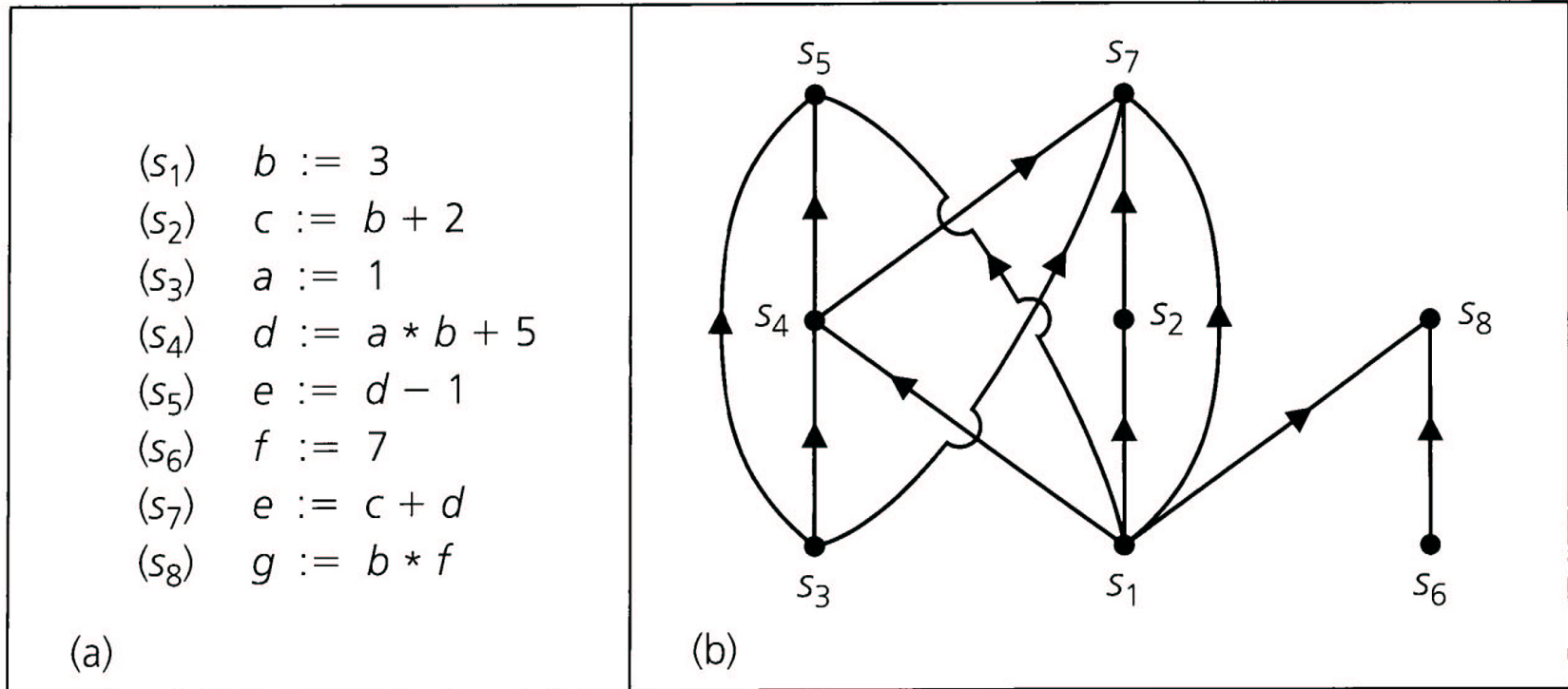


Figure 7.3



# A Few More Terms

- What are: (i) **associated undirected graph**, (ii) **path** (cannot contain duplicated vertices), (iii) **connected graph**, (iv) **length**, (v) **loop**, and (vi) **cycle**?

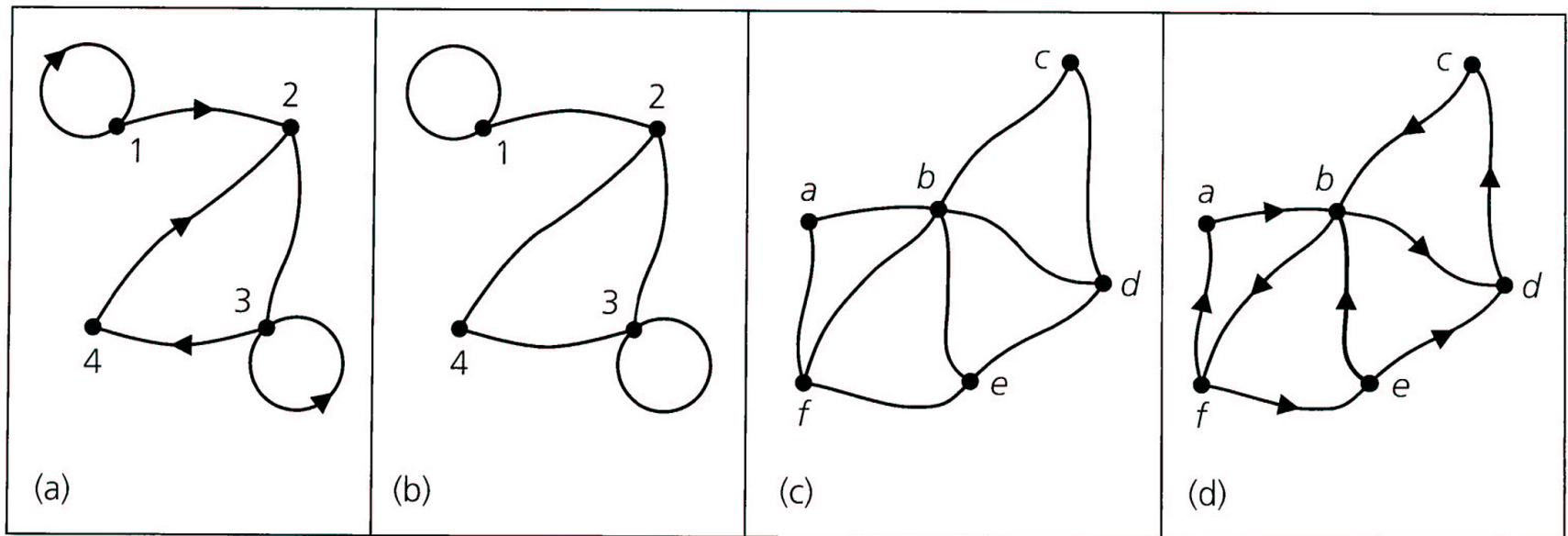


Figure 7.4

# Strongly Connected

- A directed graph  $G$  on  $V$  is called **strongly connected** if there is a path from any vertex  $x$  to any vertex  $y$
- The graph on the right is connected but not strongly connected
- The graph on the right is strongly connected and **loop-free**

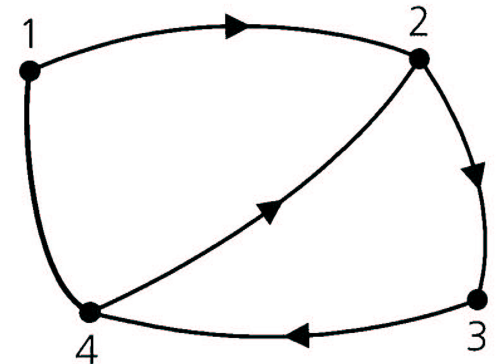
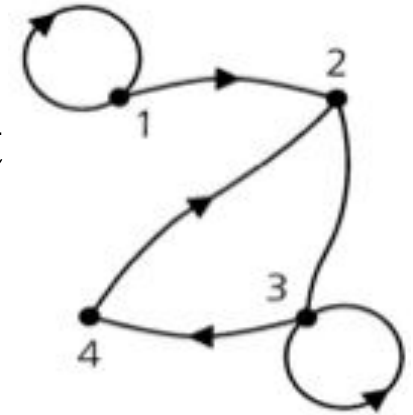


Figure 7.5

# Components

- Two components in each graph

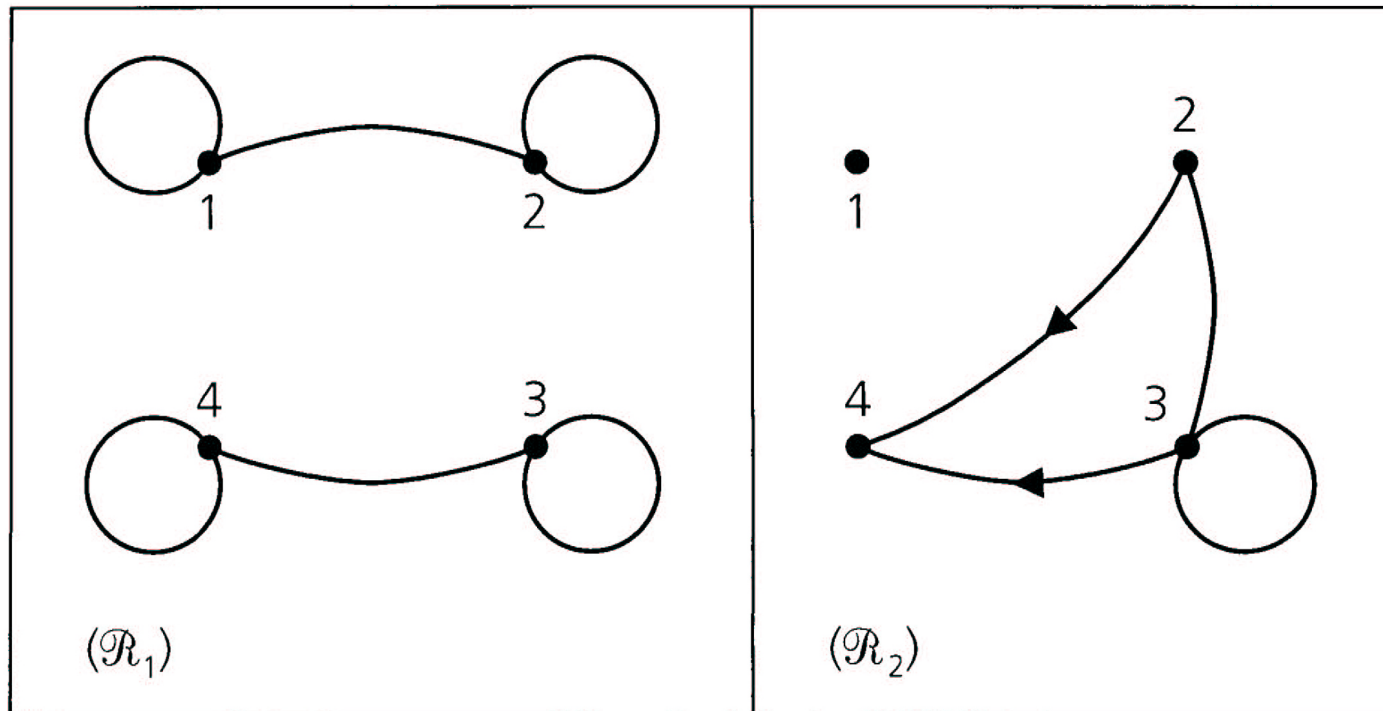


Figure 7.6

# Complete Graphs

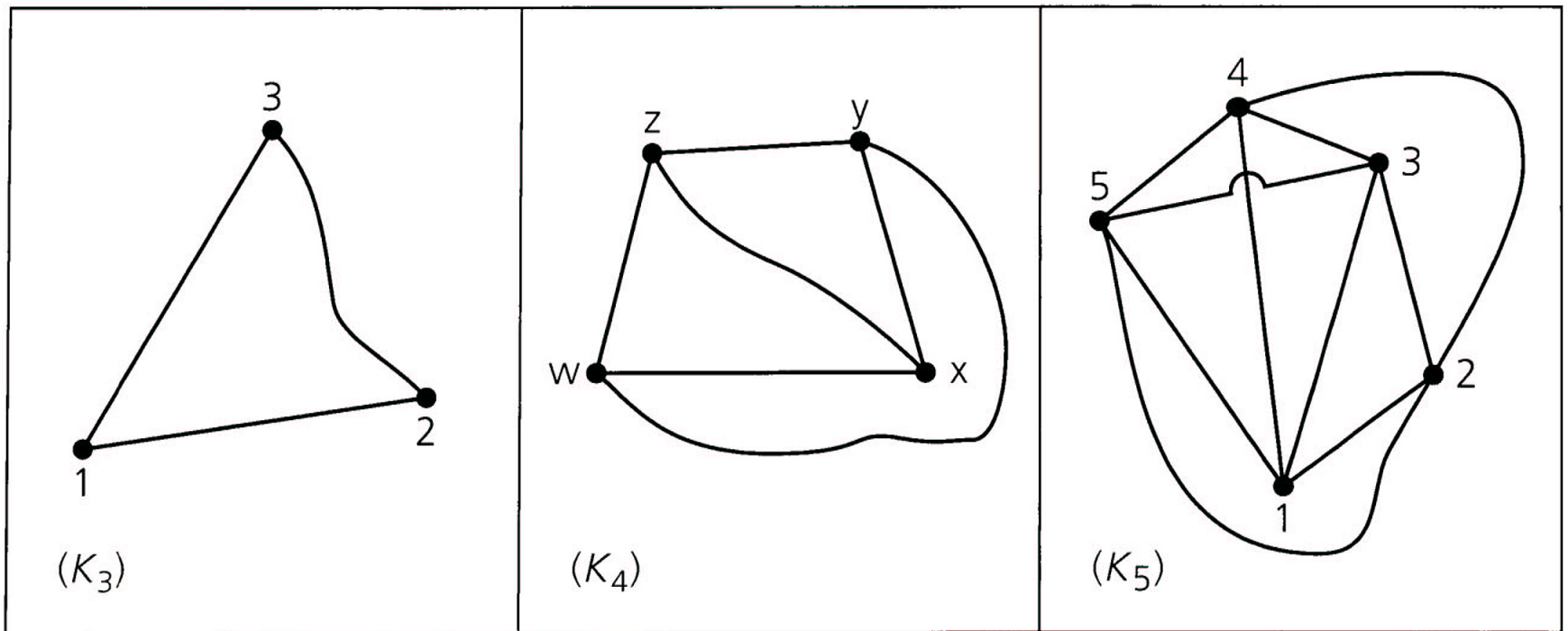
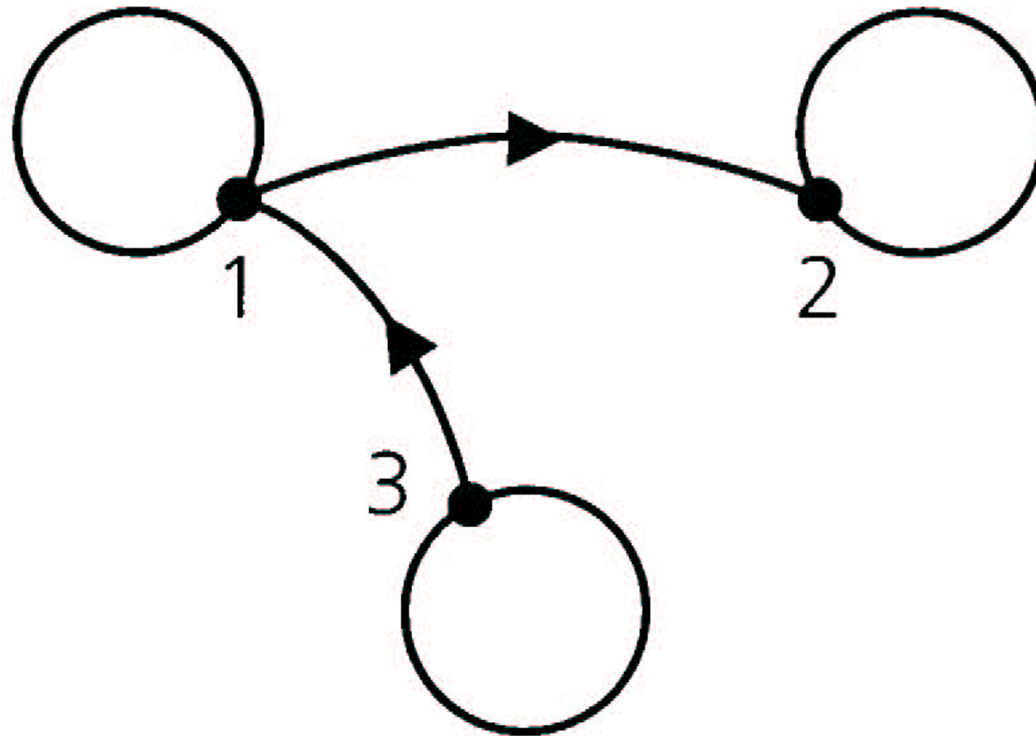


Figure 7.7

# Matrices and Graphs

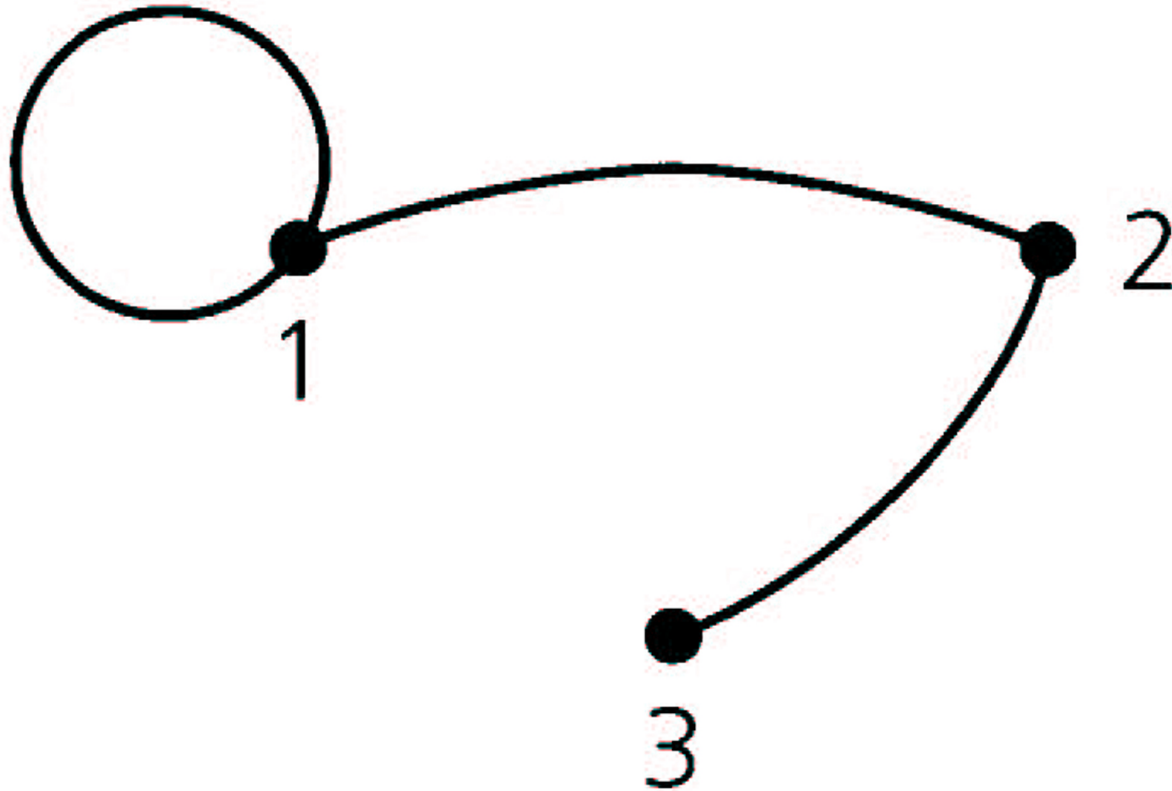
- A graph  $G$  describes a relation  $\mathcal{R}$ 
  - If  $(x,y)$  is an edge in  $G$ , then  $x\mathcal{R}y$
- Both 0-1 matrix and digraph can describe relations
  - The matrix is called the **adjacency matrix** for  $G$
  - Or a **relation matrix** for  $\mathcal{R}$

# Reflexive and Antisymmetric



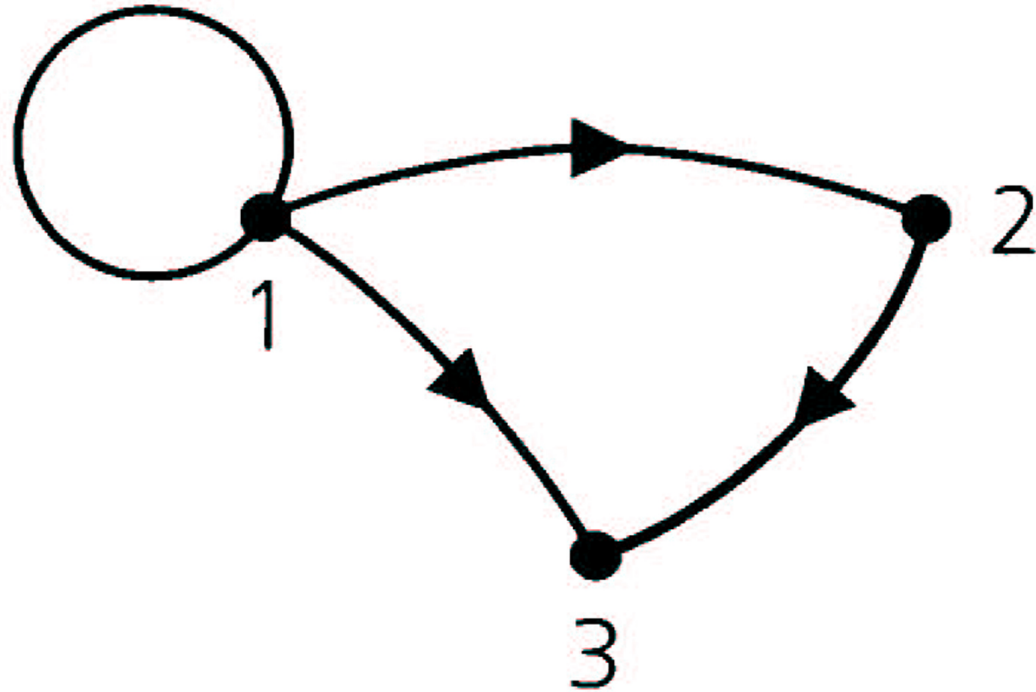
**Figure 7.8**

# Symmetric



**Figure 7.9**

# Transitive and Antisymmetric



**Figure 7.10**



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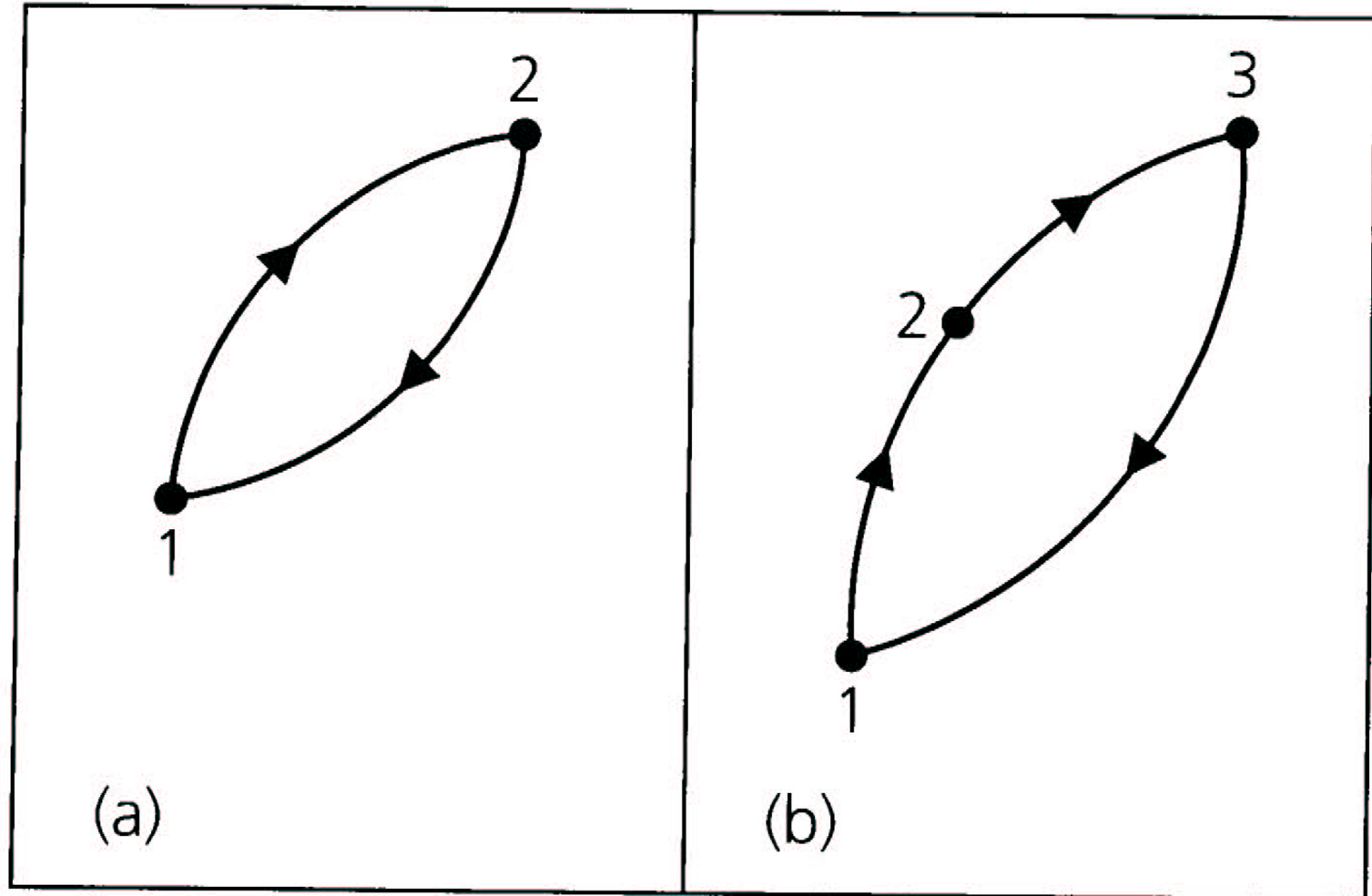
**7.4 Equivalence Rations and Partitions**

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# Partially Ordered Set

- $\mathcal{R}$  is a relation on  $A$ .  $(A, \mathcal{R})$  is called **partially ordered set** if relation  $\mathcal{R}$  on  $A$  is a partial order relation
  - Reflexive, antisymmetric, transitive
  - Also called **poset**
- Ex 7.34: Define the relation  $x\mathcal{R}y$  if  $x, y$  are the same course or if  $x$  is a prerequisite of  $y$

# Not Partial Order



**Figure 7.16**

# Hasse Diagram

- Drop loops
- Drop transitive edge
- Directions go from bottom up

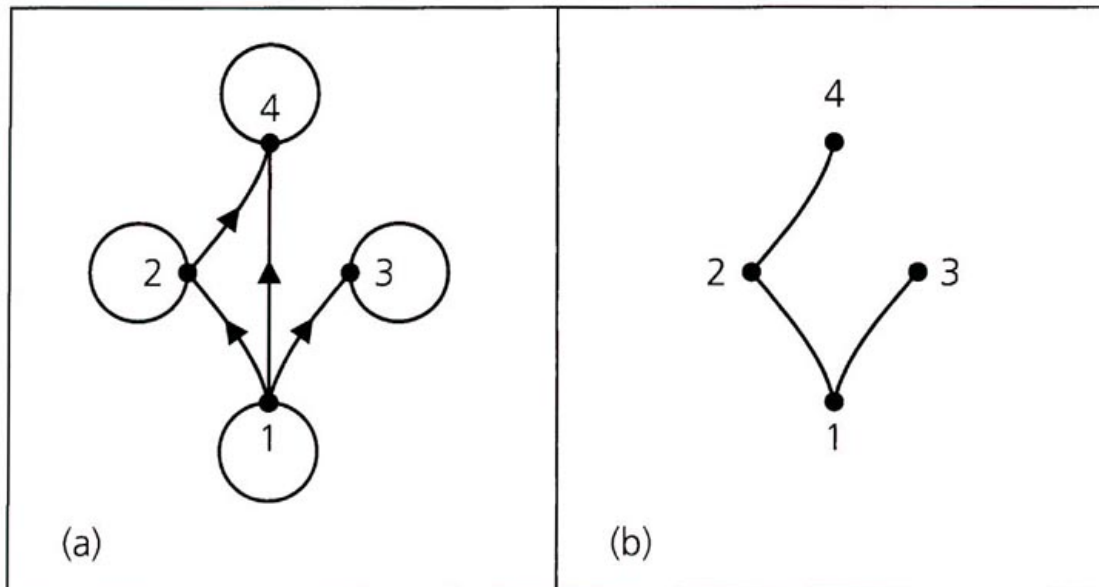


Figure 7.17

# Totally Ordered

- If  $(A, \mathcal{R})$  is a poset,  $A$  is **totally ordered** (or linearly ordered) if for any  $x$  and  $y$ , either  $x\mathcal{R}y$  or  $y\mathcal{R}x$  .
  - $\mathcal{R}$  is called a **total order** (or a linear order)

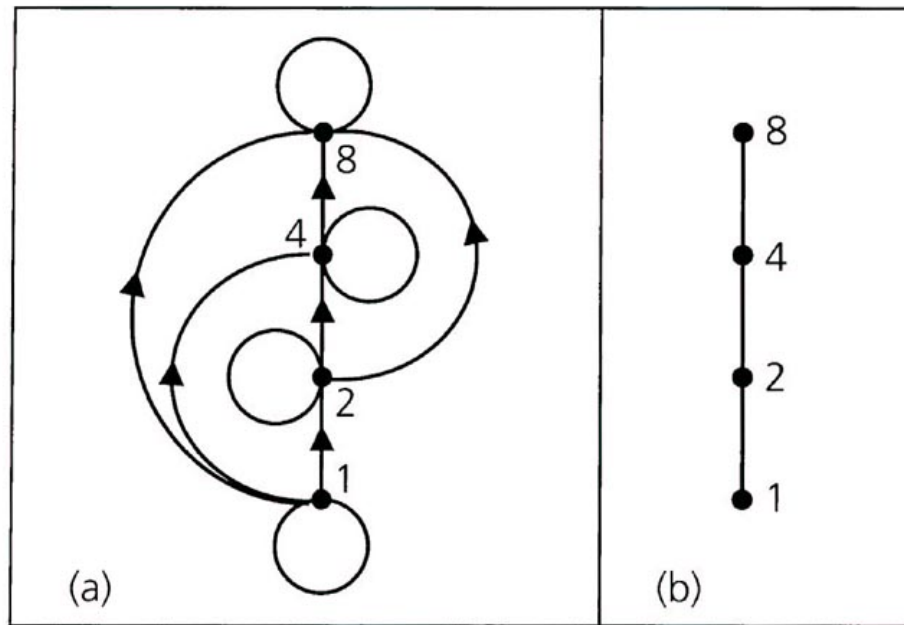
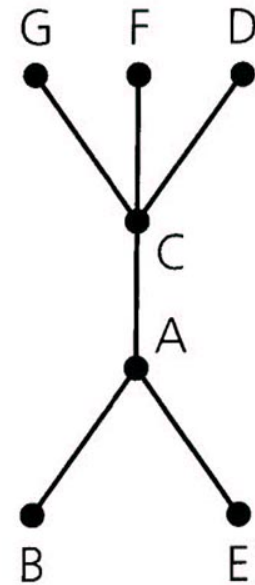


Figure 7.19

# Partial vs. Total Orders

- Consider a car manufacturer which needs to assemble 7 components into a car. The partial order is  $\mathcal{R}$  given below
  - Can the company find a total order  $\mathcal{T}$  so that  $\mathcal{R} \subseteq \mathcal{T}$  ?
  - **Topological sorting!**



**Figure 7.20**

# Topological Sorting

- Idea: Repeatedly remove the vertex that is not a source (nor an implicit source) of any edge, until we have no vertex left in the Hasse diagram

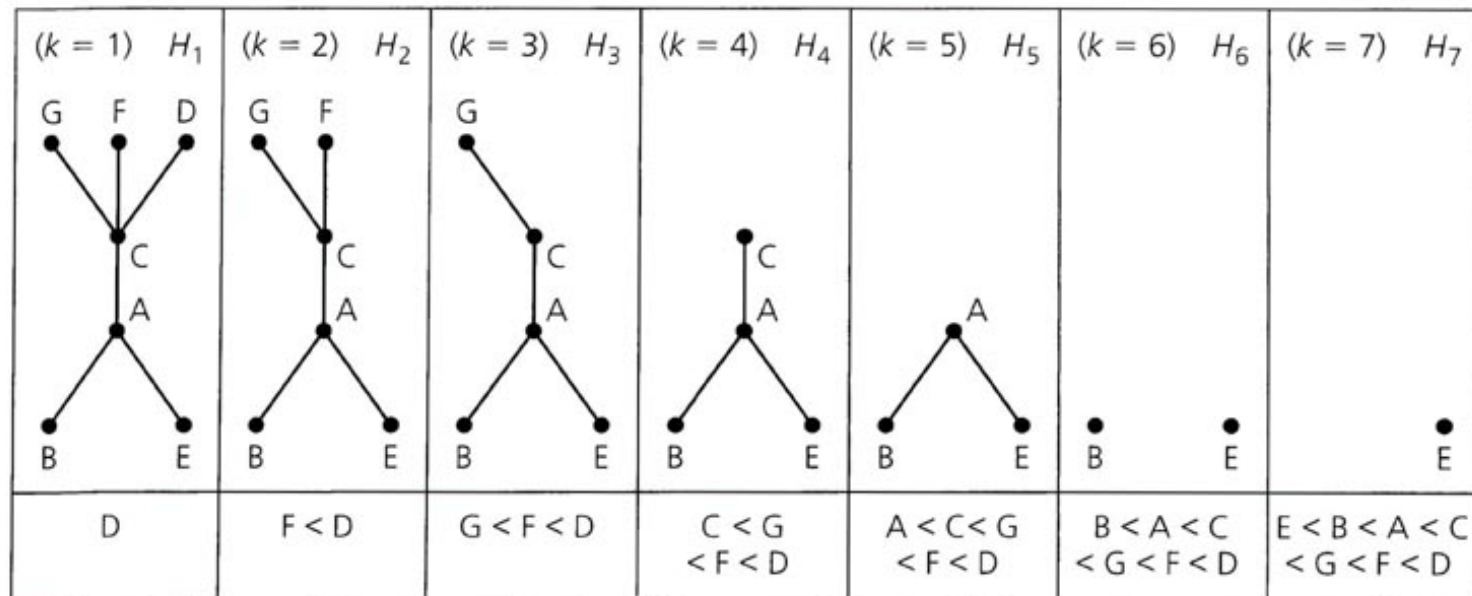


Figure 7.21

# Topological Sorting Algorithm

- Input: A partial order  $\mathcal{R}$  on a set  $A$ , where  $|A| = n$
- Step 1: Let  $k = 1$ , Let  $H_1$  be the Hasse diagram
- Step 2: Select  $v_k$  from  $H_k$ , so that no (implicitly directed) edge in  $H_k$  starts at  $v_k$
- Step 3: If  $k < n$ , remove  $v_k$  and edges terminating at  $v_k$  from  $H_k$ . Call the new Hasse  $H_{k-1}$ , and goto step 1
- Step 4: The total order that contains  $\mathcal{R}$  is

$$\mathcal{I} : v_n < v_{n-1} < \cdots < v_2 < v_1$$



# Maximal, Minimal Elements

- If  $(A, \mathcal{R})$  is a poset, an element  $x \in A$  is a **maximal element** of  $A$  if for all  $a \in A$ ,  $a \neq x \implies \neg(x\mathcal{R}a)$ . An element  $y \in A$  is a **minimal element** of  $A$  if for all  $b \in A$ ,  $b \neq y \implies \neg(b\mathcal{R}y)$
- Ex 7.42: Define  $\mathcal{R}$  be “less than or equal to” relation on  $\mathbb{Z}$ , we find that  $(\mathbb{Z}, \mathcal{R})$  is a poset with no maximal nor minimal element. How about  $(\mathbb{N}, \mathcal{R})$ ?
- A poset may have multiple maximal (minimal) elements! Recall the topological sorting algorithm.
- If  $(A, \mathcal{R})$  is a poset and  $A$  is finite,  $A$  has both a maximal and a minimum element

# Least, Greatest Elements

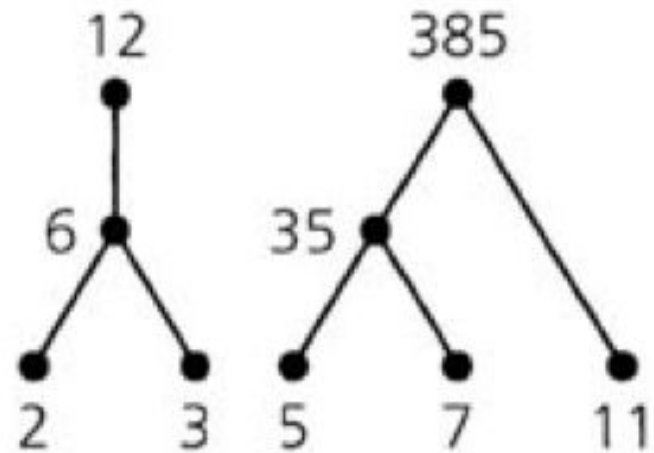
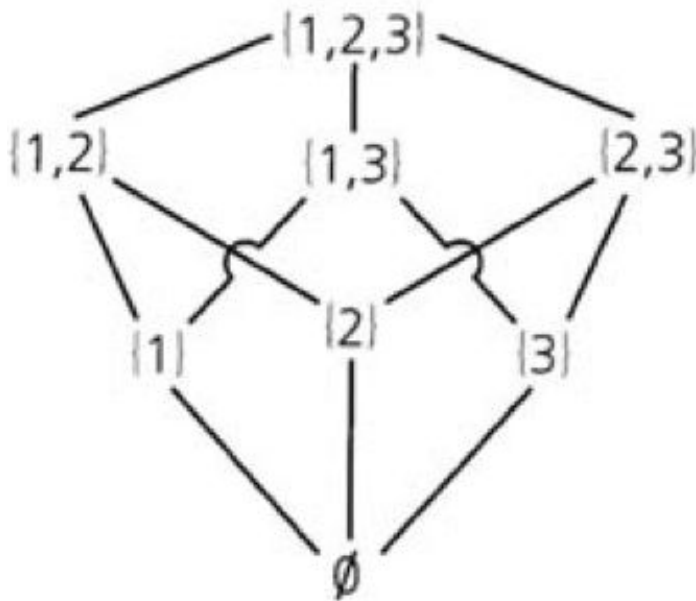
- If  $(A, \mathcal{R})$  is a poset, an element  $x \in A$  is a **least element** of  $A$  if  $x \mathcal{R} a \forall a \in A$ . An element  $y \in A$  is a **greatest element** of  $A$  if  $b \mathcal{R} y \forall b \in A$ 
  - If a poset has a greatest (least) element, the element is unique
- Ex 7.45: Define  $\mathcal{U} = \{1, 2, 3\}$ ,  $\mathcal{R}$  be subset relation
  - Poset  $(\mathcal{P}(\mathcal{U}), \subseteq)$  has  $\emptyset$  as a least element and  $\mathcal{U}$  as a greatest element
  - Let  $A$  be all the nonempty subsets of  $\mathcal{U}$ .  $(A, \subseteq)$  has  $\mathcal{U}$  as the greatest element. It has no least element, **but three minimal elements**.

# Lower and Upper Bounds

- If  $(A, \mathcal{R})$  is a poset and  $B \subseteq A$ . An element  $x \in A$  is called a **lower bound** of  $B$  if  $x \mathcal{R} b \forall b \in B$ . An element  $y \in A$  is called an **upper bound** of  $B$  if  $b \mathcal{R} y \forall b \in B$ 
  - $x' \in A$  is a **greatest lower bound (glb)** of  $B$  if it is a lower bound of  $B$  and  $x'' \mathcal{R} x'$  for any other lower bound  $x''$  of  $B$
  - $x' \in A$  is a **least upper bound (lub)** of  $B$  if it is an upper bound of  $B$  and  $x' \mathcal{R} x''$  for any other upper bound  $x''$  of  $B$
- Ex 7.47: Let  $A = \mathcal{P}(\{1, 2, 3, 4\})$  and  $\mathcal{R}$  be the subset relation on  $A$ . If  $B = \{\{1\}, \{2\}, \{1, 2\}\}$  then what are the upper bounds? What is the least upper bound? What is the greatest lower bound?
  - Lub and glb are unique

# Lattice

- A poset  $(A, \mathcal{R})$  is called a **lattice** if for all  $x, y \in A$  the elements  $\text{lub}\{x, y\}$  and  $\text{glb}\{x, y\}$  both exist in  $A$



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# Equivalence Relations

- A relation  $\mathcal{R}$  on  $A$  is an **equivalence relation** if it's reflexive, symmetric, and transitive.
- Ex 1: For  $A \neq \emptyset$ , the equality relation is an equivalence relation, in which two elements are related if they are identical.
- Ex 2: Consider a relation on  $\mathbb{Z}$ , where  $x\mathcal{R}y$  if  $x - y$  is a multiple of 2.
  - How does this relation **split**  $\mathbb{Z}$  into two subsets?

# Partition

- Let  $A$  be a set and  $I$  be an index set, where  $A_i$  is not empty and  $A_i \subseteq A$ , for all  $i \in I$ .  $\{A_i\}_{i \in I}$  is a **partition** of  $A$  if

- $A = \bigcup_{i \in I} A_i$

- $A_i \cap A_j = \emptyset$  for all  $i \neq j; i, j \in I$

Each subset  $A_i$  is a **cell**, or **block** of the partition

- Ex 7.52: For  $A = \{1,2,3,\dots,10\}$ , the following are partitions of  $A$ 
  - $\{\{1,2,3,4,5\}, \{6,7,8,9,10\}\}$
  - $A_i = \{i, i+5\}, 1 \leq i \leq 5$

# Equivalence Class

- Let  $\mathcal{R}$  be an **equivalence relation** on  $A$ . The equivalence class of  $x \in A$ , denoted as  $[x]$ , is defined by  $[x] = \{y \mid y \in A, y \mathcal{R} x\}$
- Ex 7.52:  $\mathcal{R}$  is a equivalence relation on  $\mathbb{Z}$ , where  $x \mathcal{R} y$  if  $4 \mid (x - y)$ . The four equivalence classes are
  - $[0] = \{4k \mid k \in \mathbb{Z}\}$
  - $[1] = \{4k + 1 \mid k \in \mathbb{Z}\}$
  - $[2] = \{4k + 2 \mid k \in \mathbb{Z}\}$
  - $[3] = \{4k + 3 \mid k \in \mathbb{Z}\}$



# Properties of Equivalence Class

- Let  $\mathcal{R}$  is an **equivalence relation** on  $A$ , and  $x, y \in A$ .
  - $x \in [x]$
  - $x\mathcal{R}y$  iff  $[x] = [y]$
  - $[x] = [y]$  or  $[x] \cap [y] = \emptyset$
- This theorem tells us the distinct equivalence classes given by  $\mathcal{R}$  gives us a partition of  $A$

# Examples of Partitions

- Ex 7.56 (a) : Let  $A = \{1, 2, 3, 4, 5\}$  and  $\mathcal{R} = \{(1, 1), (2, 2), (2, 3), (3, 2), (3, 3), (4, 4), (4, 5), (5, 4), (5, 5)\}$   
what's the corresponding partition?
- Ex 7.56 (b): Function  $f : A \rightarrow B$ , where  $A = \{1, 2, 3, 4, 5, 6, 7\}$  and  $B = \{x, y, z\}$ ,  $f$  is defined as  $\{(1, x), (2, x), (3, x), (4, y), (5, z), (6, y), (7, x)\}$

We define a relation  $\mathcal{R}$  by  $a\mathcal{R}b$  if  $f(a) = f(b)$ . What is the partition determined by  $\mathcal{R}$  ?

# Examples of Partitions (cont.)

- If an equivalence relation  $\mathcal{R}$  on  $A = \{1, 2, 3, 4, 5, 6, 7\}$  results in the partition  $A = \{1, 2\} \cup \{3\} \cup \{4, 5, 7\} \cup \{6\}$ , what is  $\mathcal{R}$ ? What's the size of it?

$$\mathcal{R} = (\{1, 2\} \times \{1, 2\}) \cup (\{3\} \times \{3\}) \cup (\{4, 5, 7\} \times \{4, 5, 7\}) \cup (\{6\} \times \{6\})$$

# Equivalence Class and Partition

- For a set  $A$ 
  - Any equivalence relation  $\mathcal{R}$  on  $A$  leads to a partition of  $A$
  - Any partition of  $A$  gives an equivalence relation  $\mathcal{R}$  on  $A$
- For any set  $A$ , there is a one-to-one correspondence between the set of equivalence relations on  $A$  and the set of partitions of  $A$ .
  - So counting the number of partitions is the same as counting 1-1 functions.

# Outline

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**7.1 Relations Revisited: Properties of Relations**

**7.2 Computer Recognition: Zero-One Matrices and Directed Graphs**

**7.3 Partial Orders: Hasse Diagrams**

**7.4 Equivalence Relations and Partitions**

**7.5 Finite State Machines: The Minimization Process**

# Redundant States

- **Redundant state**: A state that can be eliminated because other states will perform its function
- Consider a finite state machine  $M = (S, \mathcal{I}, \mathcal{O}, \nu, \omega)$ ,  
Let a relation  $s_1 E_1 s_2$  if  $\omega(s_1, x) = \omega(s_2, x)$  for all  $x \in \mathcal{I}$ 
  - $E_1$  is called **1-equivalent**.
- $s_1 E_k s_2$  if  $\omega(s_1, x) = \omega(s_2, x)$  for all  $x \in \mathcal{I}^k$ 
  - $E_k$  is called **k-equivalent**
- $s_1 E s_2$  if  $s_1 E_k s_2$  is true for all  $k \geq 1$ 
  - $E$  is called **equivalent**

# Minimization Algorithm

- To get rid of **redundant states**
- Step 1: Let  $k=1$ , find states that are 1-equivalent by examining the output rows in the state table. This gives partition  $P_1$  and relation  $E_1$
- Step 2: When  $P_k$  is found, we obtain  $P_{k+1}$  by knowing that if  $s_1 E_k s_2$ , then  $s_1 E_{k+1} s_2$  when  $\nu(s_1, x) E_k \nu(s_2, x) \forall x \in \mathcal{I}$ 
  - This is true if  $\nu(s_1, x)$  and  $\nu(s_2, x)$  are in the same cell of  $P_k$
- Step 3: If  $P_{k+1} = P_k$ , we are done, o.w. goto step 2

# A Simple Example

- Ex 7.60: If  $\mathcal{I} = \mathcal{O} = \{0, 1\}$ , the state table is given below. What is  $P_1$ ?  $P_1 : \{s_1\}, \{s_2, s_5, s_6\}, \{s_3, s_4\}$
- Show  $\nu(s_3, x)E_1\nu(s_4, x)$ , and thus?
- Show  $\neg[\nu(s_5, x)E_1\nu(s_6, x)]$ , and thus?
- $P_2 : \{s_1\}, \{s_2, s_5\}, \{s_6\}, \{s_3, s_4\}$
- Since  $P_1 \neq P_2$ , we need to get  $P_3$ 
  - Because  $P_3 = P_2$ , we stop here
  - $s_5, s_4$  are **redundant states**

**Table 7.1**

	$\nu$		$\omega$	
	0	1	0	1
$s_1$	$s_4$	$s_3$	0	1
$s_2$	$s_5$	$s_2$	1	0
$s_3$	$s_2$	$s_4$	0	0
$s_4$	$s_5$	$s_3$	0	0
$s_5$	$s_2$	$s_5$	1	0
$s_6$	$s_1$	$s_6$	1	0



# Refinement

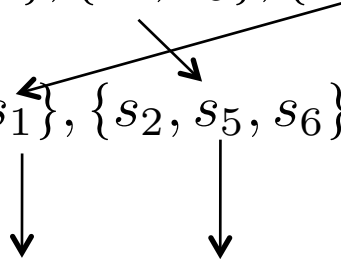
- $P_2$  is called a refinement of  $P_1$ ,  $P_2 \leq P_1$ , if every cell of  $P_2$  is contained in a cell of  $P_1$ . When  $P_2 \leq P_1$  and  $P_2 \neq P_1$ , we write  $P_2 < P_1$ .
- In the minimization process, if  $k \geq 1$  and  $P_k = P_{k+1}$ , then  $P_{r+1} = P_r$  for all  $r \geq k+1$

# Distinguishing String

- A sample string with length  $k+1$  that leads to different outputs for states  $s_1$  and  $s_2$
- Ex 7.61: Find the minimal distinguish string for  $s_2$  and  $s_6$  in the finite state machine of Ex 7.60

$P_2 : \{s_1\}, \{s_2, s_5\}, \{s_6\}, \{s_3, s_4\}$

$P_1 : \{s_1\}, \{s_2, s_5, s_6\}, \{s_3, s_4\}$



**Table 7.1**

	$v$		$\omega$	
	0	1	0	1
$s_1$	$s_4$	$s_3$	0	1
$s_2$	$s_5$	$s_2$	1	0
$s_3$	$s_2$	$s_4$	0	0
$s_4$	$s_5$	$s_3$	0	0
$s_5$	$s_2$	$s_5$	1	0
$s_6$	$s_1$	$s_6$	1	0

# Take-home Exercises

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- Exercise 7.1: 1, 5, 6, 9, 17
- Exercise 7.2: 4, 14, 17, 18, 26
- Exercise 7.3: 1, 7, 18, 23, 25
- Exercise 7.4: 2, 6, 7, 12, 14
- Exercise 7.5: 1, 3