

# **CS 5244: Introduction to Cyber Physical Systems**

## **Unit 9: Composition of State Machines (Ch. 5)**

**Instructor: Cheng-Hsin Hsu**

**Acknowledgement: The instructor thanks Profs. Edward A. Lee & Sanjit  
A. Seshia at UC Berkeley for sharing their course materials**

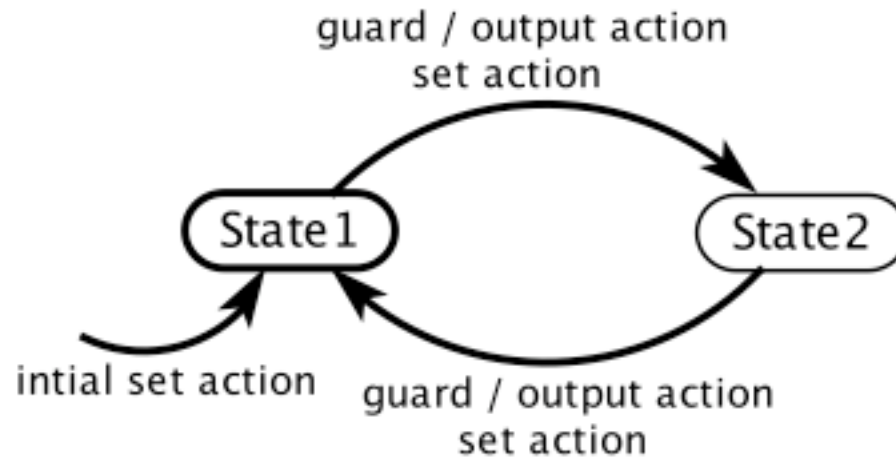
# Modeling with State Machines

## Questions:

- How to represent the system for:
  - Systematic analysis
  - So that a computer program can manipulate it
- How to model its environment
- **How to compose subsystems to make bigger systems**
- How to check whether the system satisfies its specification in its operating environment

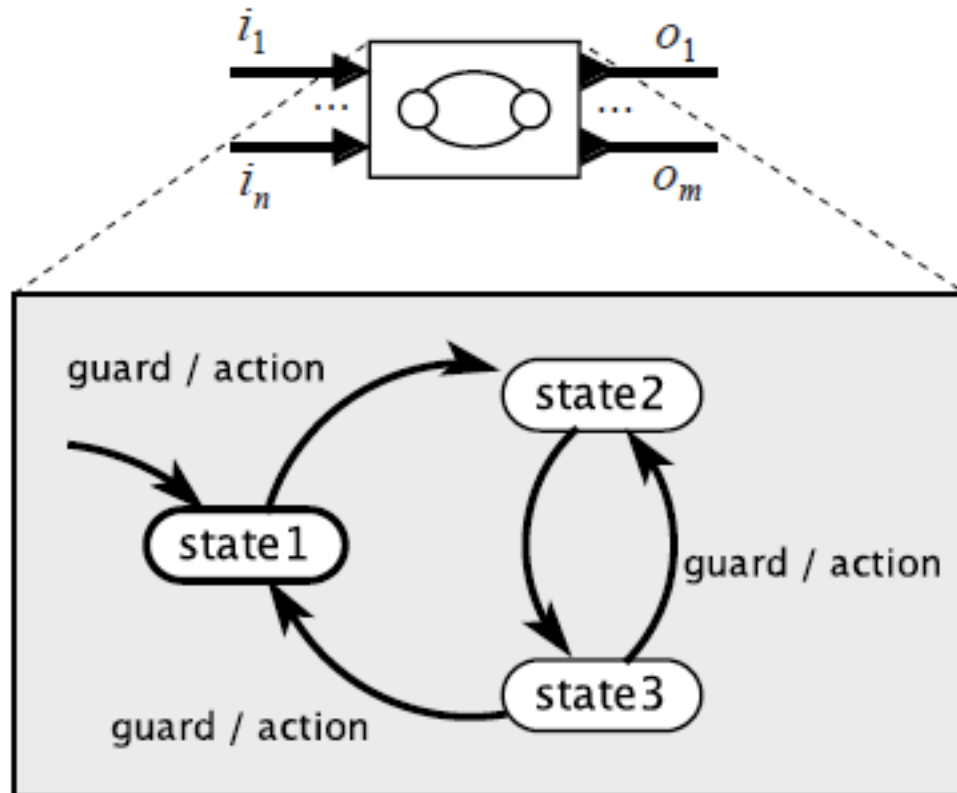
# Notation for Extended State Machines

variable declaration(s)  
input declaration(s)  
output declaration(s)



# Actor Model for State Machines

Expose inputs and outputs, enabling composition:



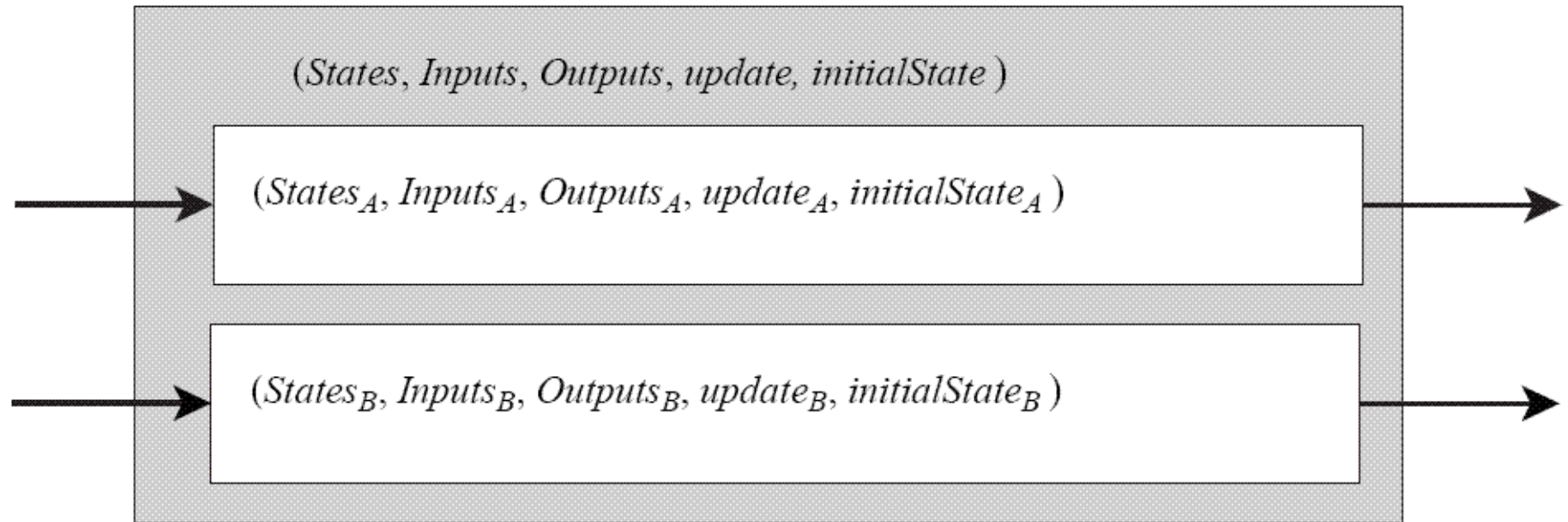
# Composition of State Machines

Side-by-side composition

Cascade composition

Feedback composition

# Side-by-Side Composition



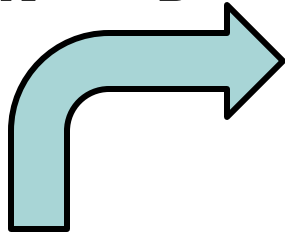
A key question: When do these machines react?

Two possibilities:

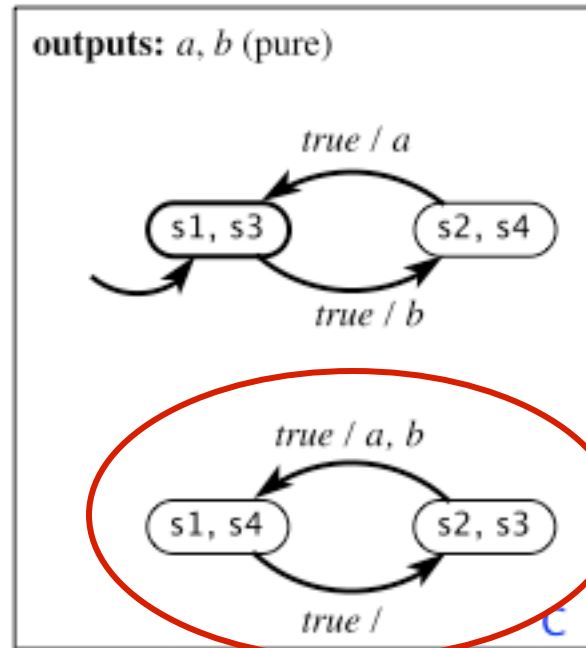
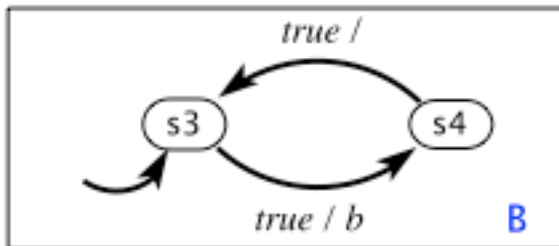
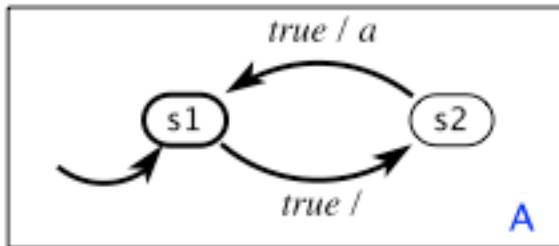
- Together (synchronous composition)
- Independently (asynchronous composition)

# Synchronous Composition

$$S_C = S_A \times S_B$$



outputs:  $a, b$  (pure)

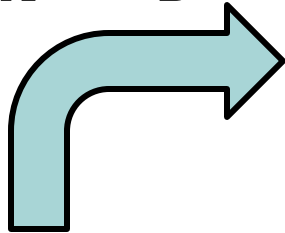


*Synchronous composition*

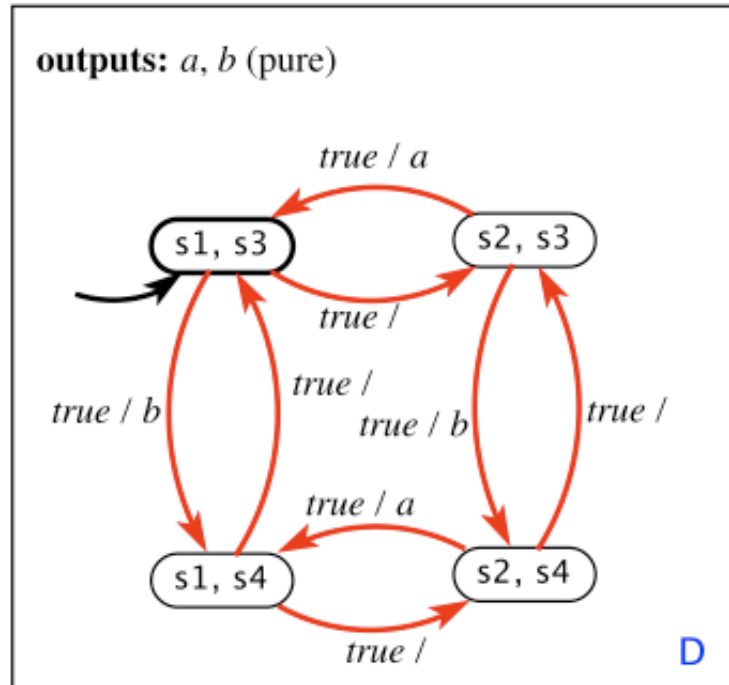
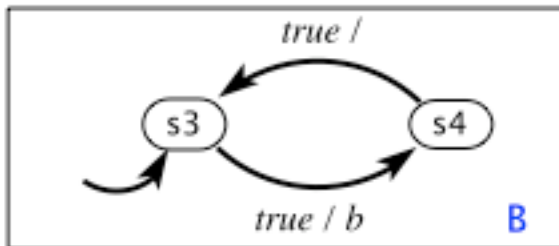
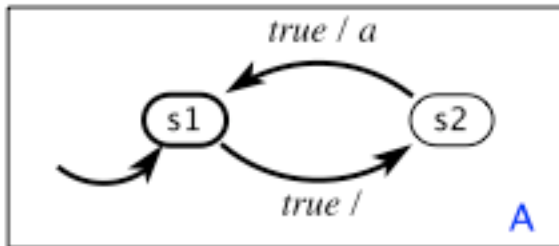
Note that these two states are not *reachable*.

# Asynchronous Composition

$$S_C = S_A \times S_B$$



outputs:  $a, b$  (pure)

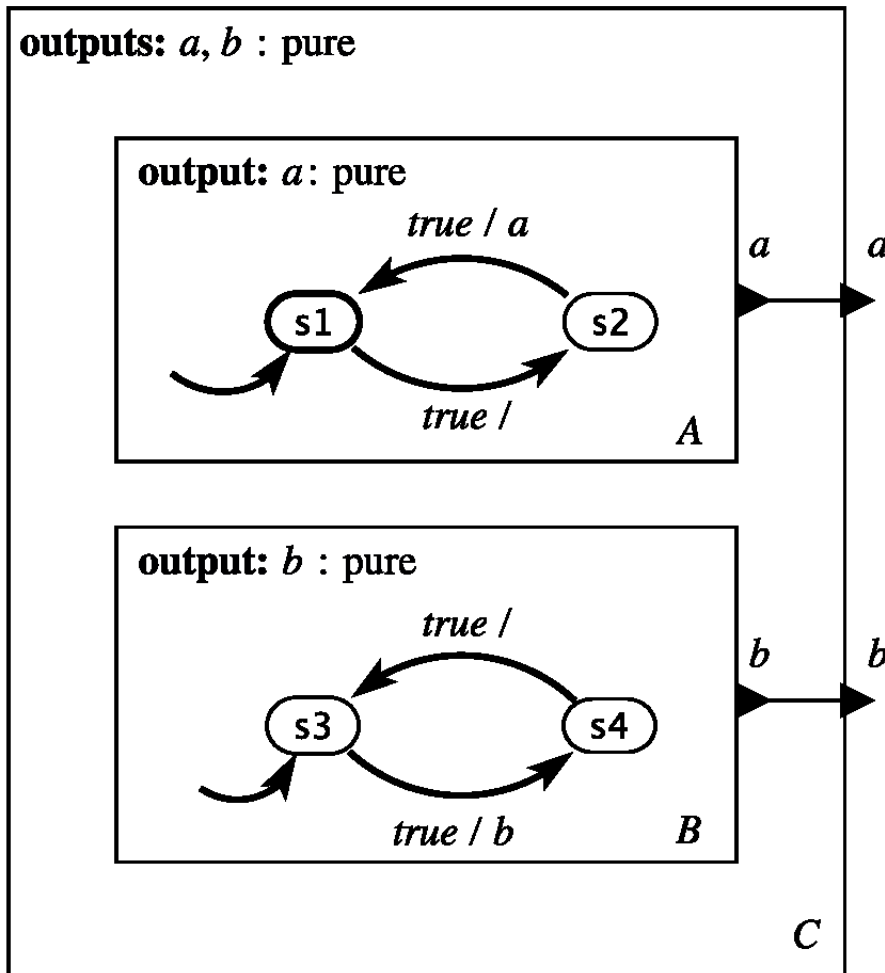


*Asynchronous composition using interleaving semantics*

Note that now all states are reachable.



# Syntax vs. Semantics



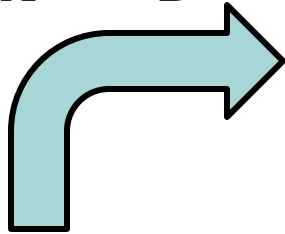
*Synchronous  
or  
Asynchronous  
composition?*

*If asynchronous,  
does it allow  
simultaneous  
transitions in  
A & B?*

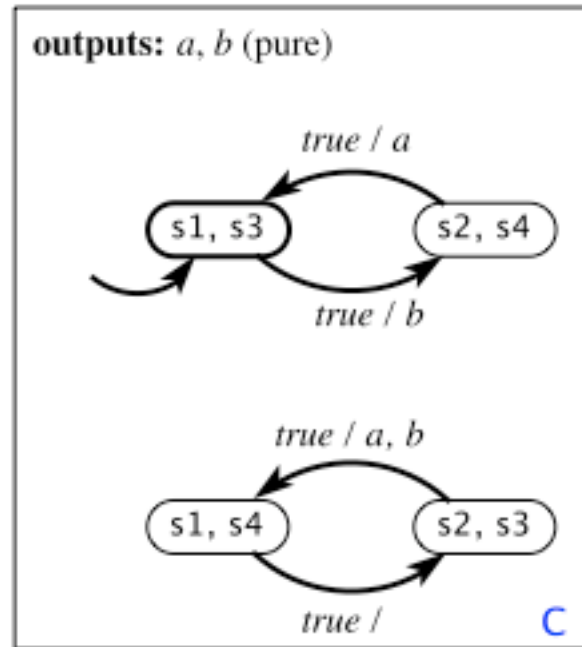
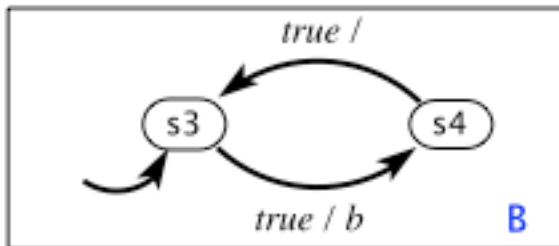
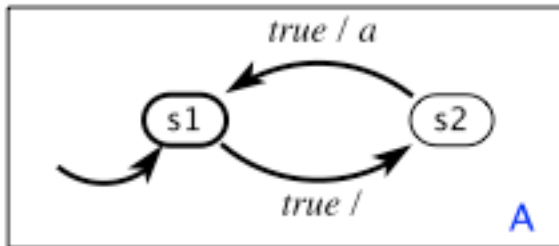
# Asynchronous composition is *not* synchronous composition with stuttering transitions.

Stuttering is a reaction where no output is produced and the state is not changed.

$$S_C = S_A \times S_B$$



outputs:  $a, b$  (pure)



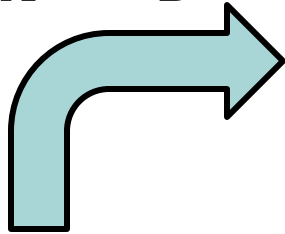
*Synchronous composition*

*These two FSMs cannot stutter.  
If they react, they change state.*

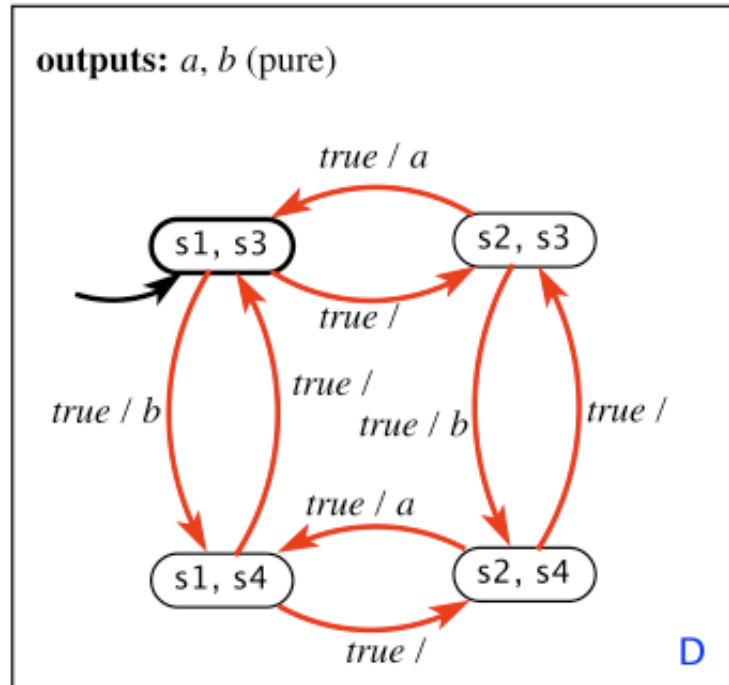
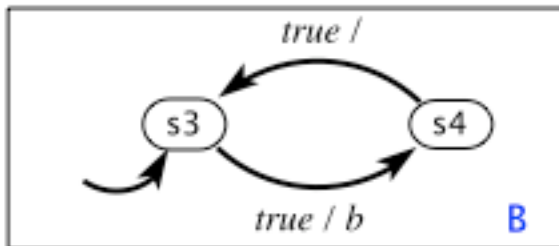
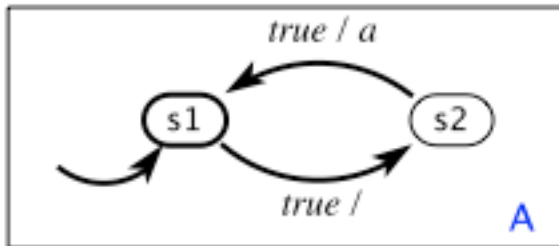
# Asynchronous composition is *not* synchronous composition with stuttering transitions.

Stuttering is a reaction where no output is produced and the state is not changed.

$$S_C = S_A \times S_B$$



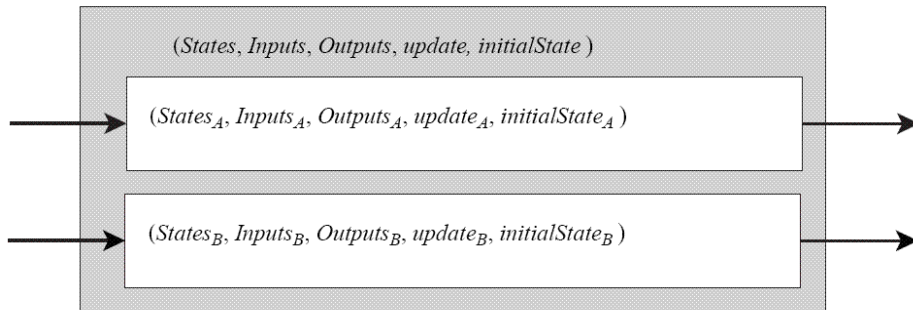
outputs:  $a, b$  (pure)



*Asynchronous composition with interleaving semantics*

*These two FSMs cannot stutter. If they react, they change state.*

# Side-by-Side Synchronous Composition



**Definition of the side-by-side composite machine:**

$$States = States_A \times States_B$$

$$Inputs = Inputs_A \times Inputs_B$$

$$Outputs = Outputs_A \times Outputs_B$$

$$initialState = (initialState_A, initialState_B)$$

$$((s_A(n+1), s_B(n+1)), (y_A(n), y_B(n)))$$

$$= update((s_A(n), s_B(n)), (x_A(n), x_B(n))),$$

where

$$(s_A(n+1), y_A(n)) = update_A(s_A(n), x_A(n)) \text{ and}$$

$$(s_B(n+1), y_B(n)) = update_B(s_B(n), x_B(n))$$

# Asynchronous Composition

$M_1 = (S_1, I_1, O_1, U_1, s_{10})$  and  $M_2 = (S_2, I_2, O_2, U_2, s_{20})$

$M$  is the asynchronous composition of  $M_1$  and  $M_2$   
 $= (S_1 \times S_2, I_1 \times I_2, O_1 \times O_2, \mathbf{U}, (s_{10}, s_{20}))$

where

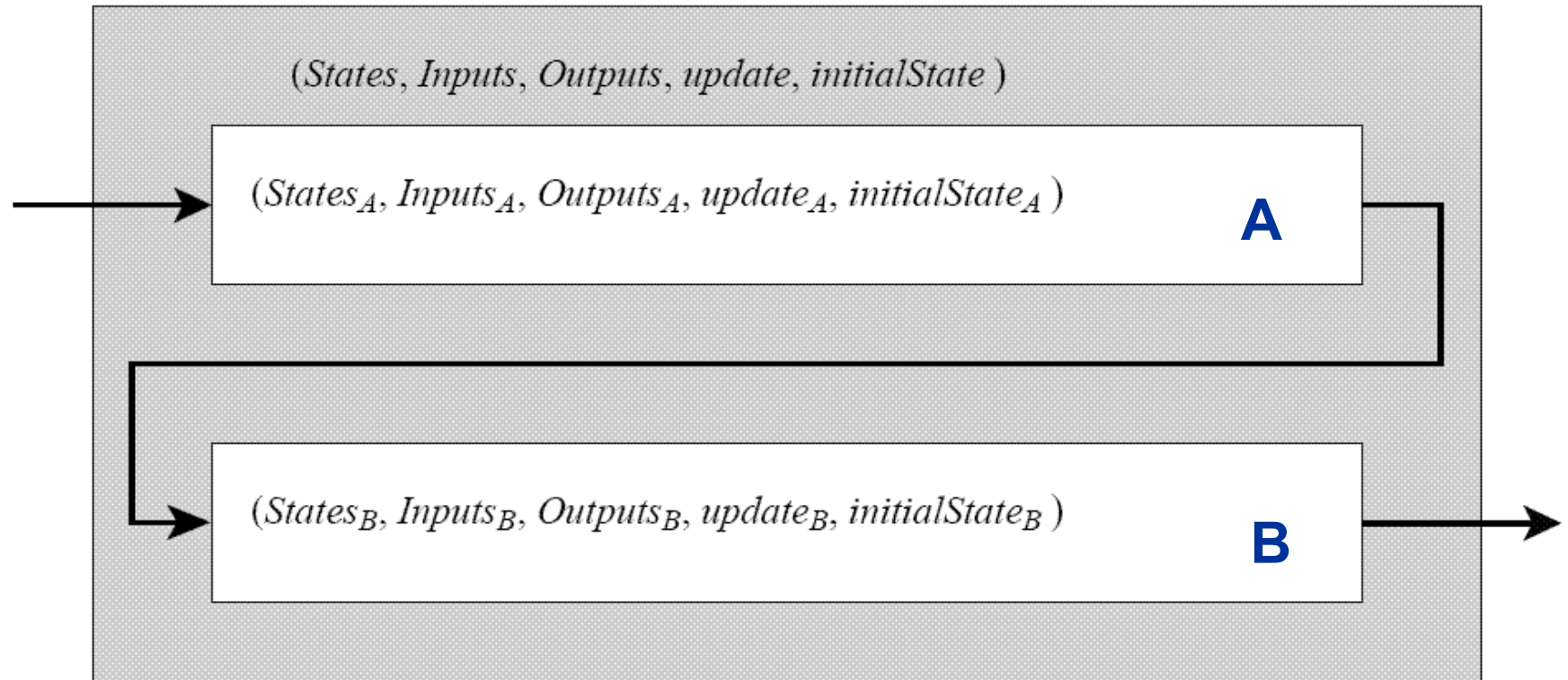
$U((s_1, s_2), (i_1, i_2)) = ((s_1', s_2'), (o_1, o_2))$

and

$(s_1', o_1) = U_1(s_1, i_1)$  AND  $s_2' = s_2$  &  $o_2$  is absent  
OR  $(s_2', o_2) = U_2(s_2, i_2)$  AND  $s_1' = s_1$  &  $o_1$  is absent

*(note interleaving semantics)*

# Cascade Composition



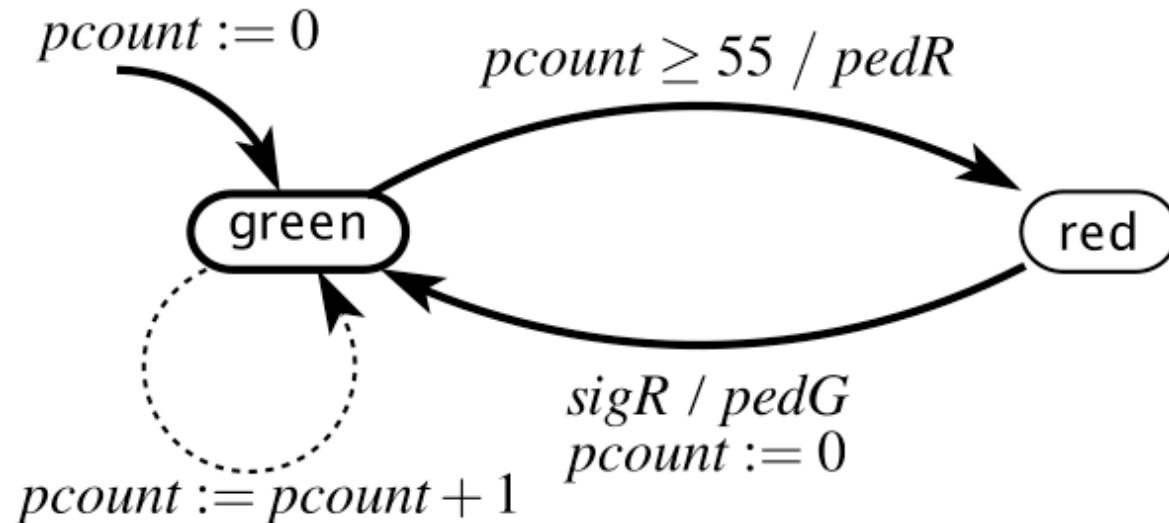
*Output port(s) of A connected to input port(s) of B*

# Example: Pedestrian Light

**variable:**  $pcount: \{0, \dots, 55\}$

**input:**  $sigR: \text{pure}$

**outputs:**  $pedG, pedR: \text{pure}$



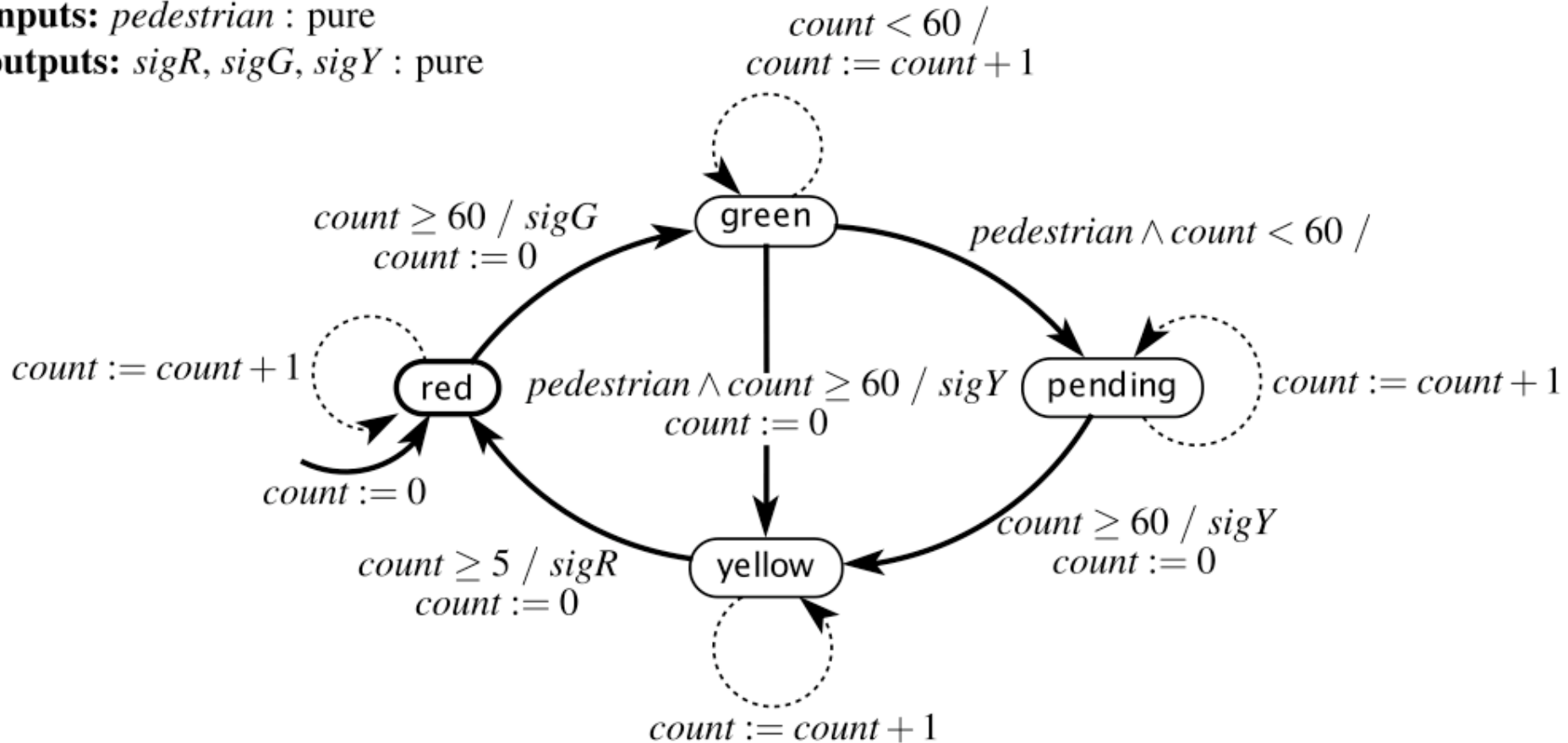
*This light stays green for 55 seconds, then goes red.  
Upon receiving a  $sigR$  input, it repeats the cycle.*

# Example: Car Light

**variable:**  $count: \{0, \dots, 60\}$

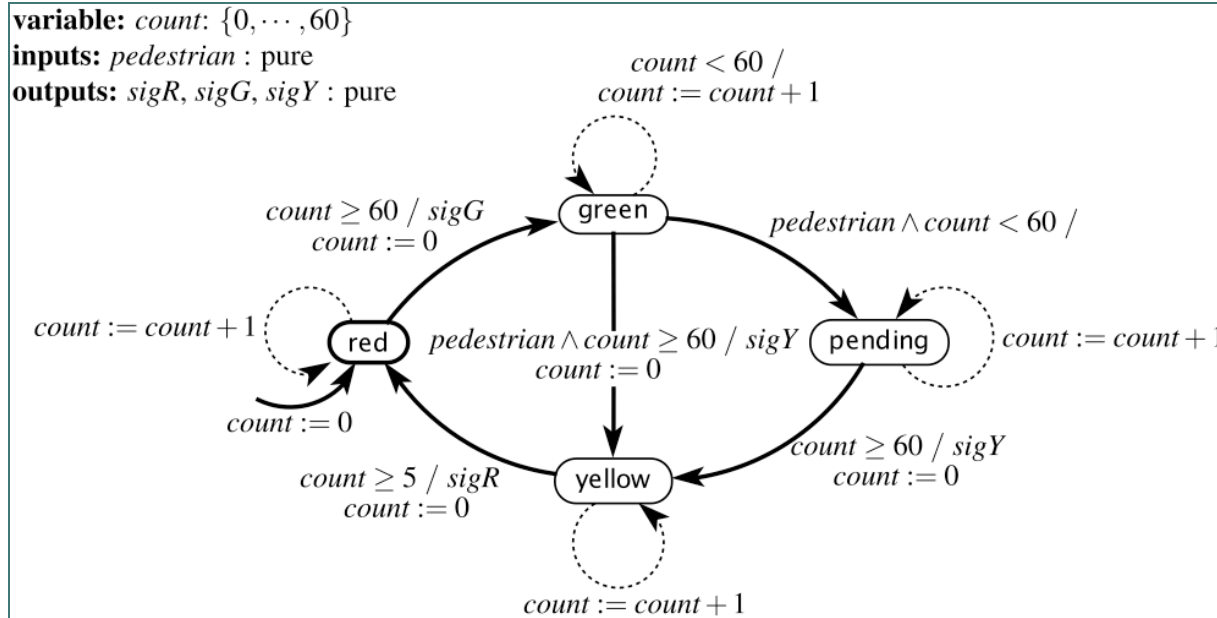
**inputs:**  $pedestrian: pure$

**outputs:**  $sigR, sigG, sigY: pure$





# Pedestrian Light with Car Light

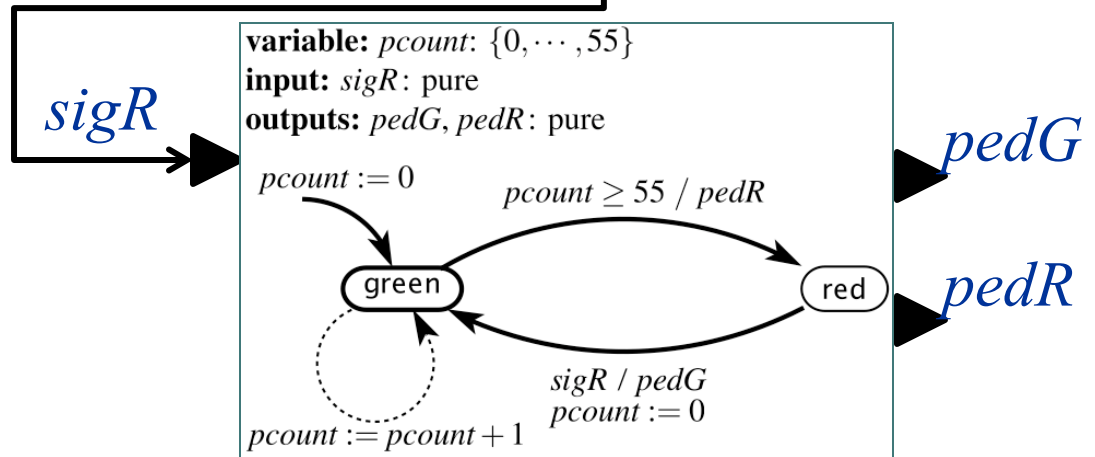


$sigY$

$sigG$

$sigR$

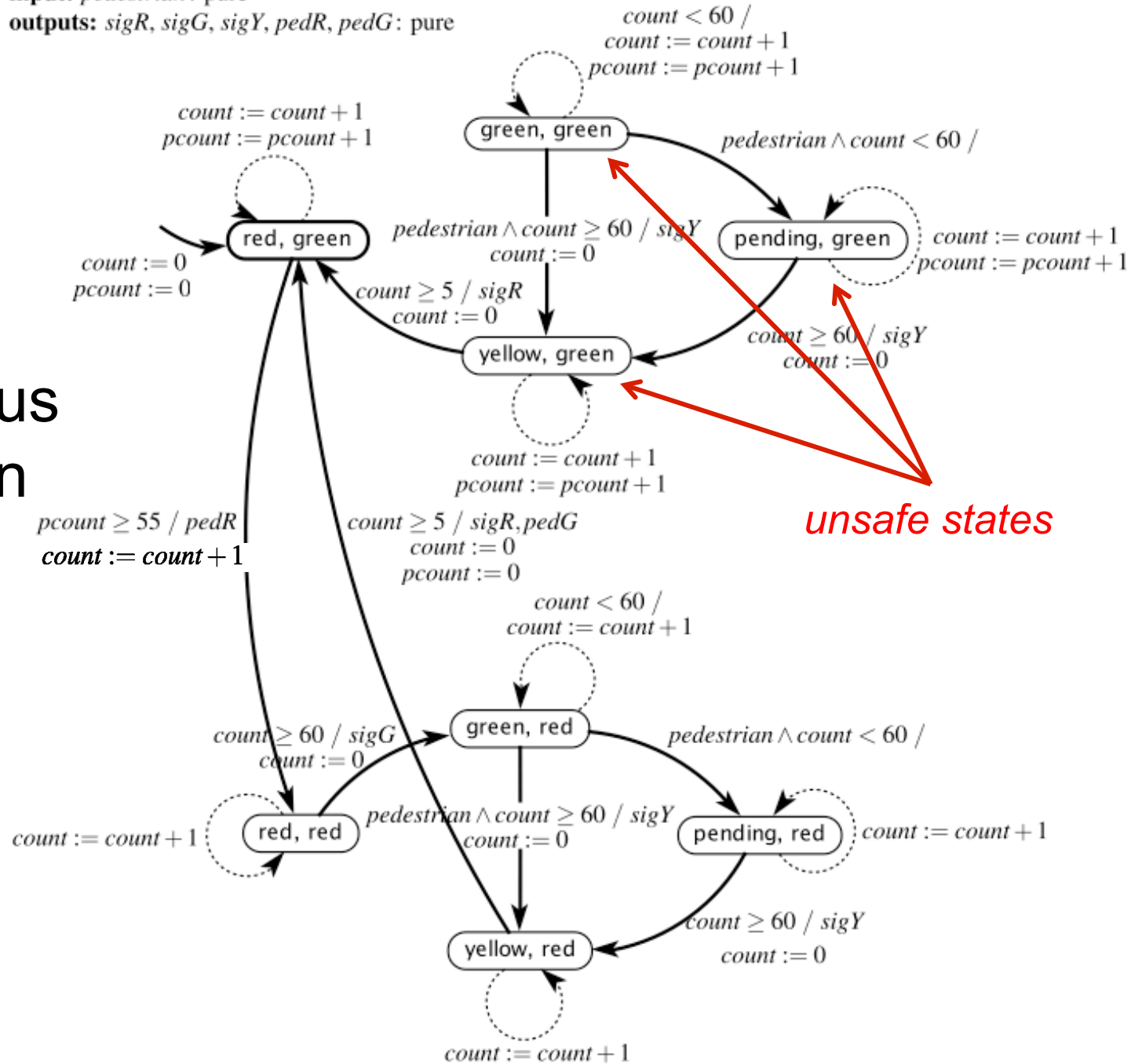
What is the size of the state space of the composite machine?



**variables:** *count*: {0, ..., 60}, *pcount*: {0, ..., 55}

**input:** *pedestrian*: pure

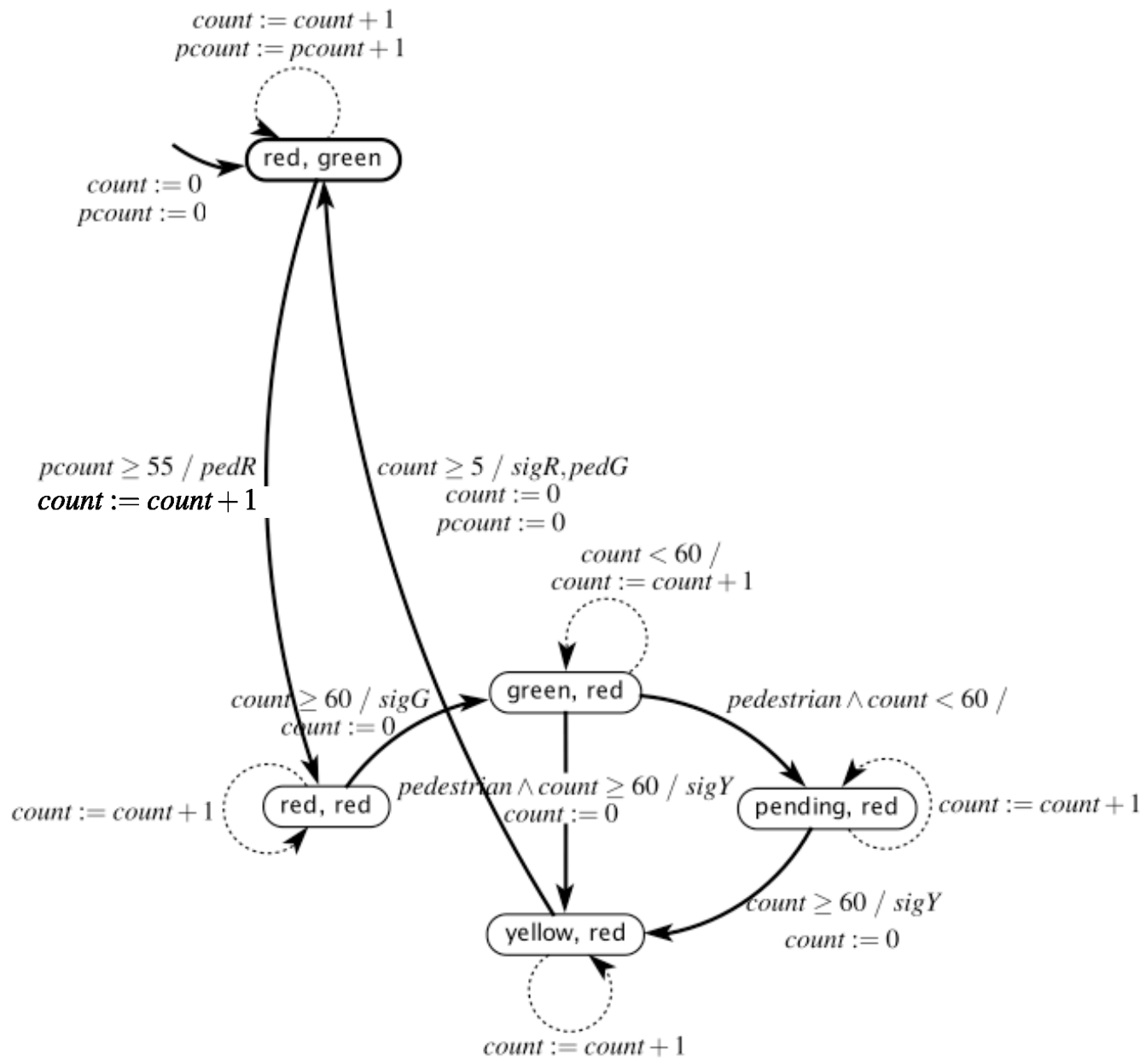
**outputs:** *sigR*, *sigG*, *sigY*, *pedR*, *pedG*: pure



# Synchronous composition

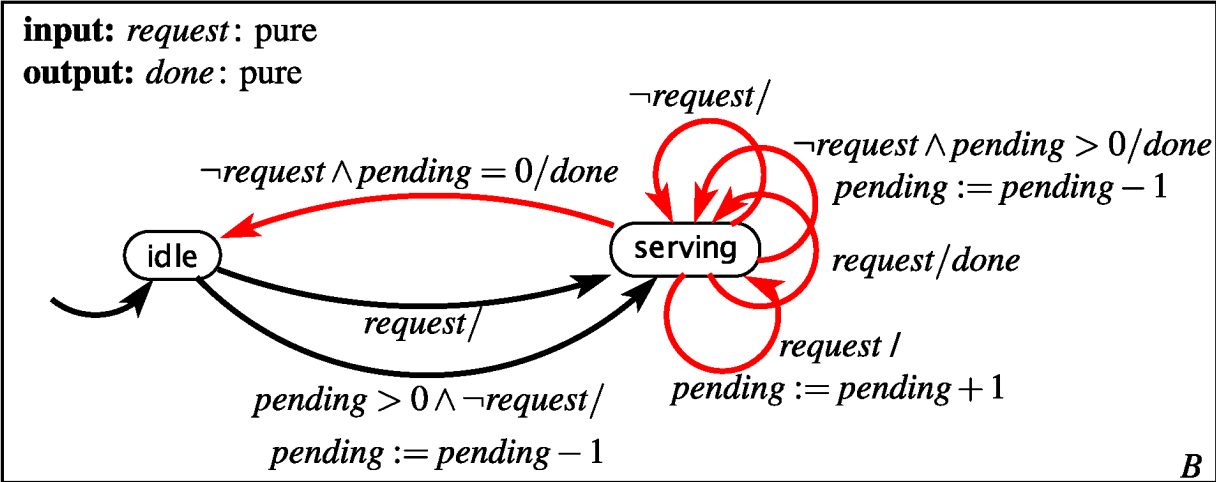
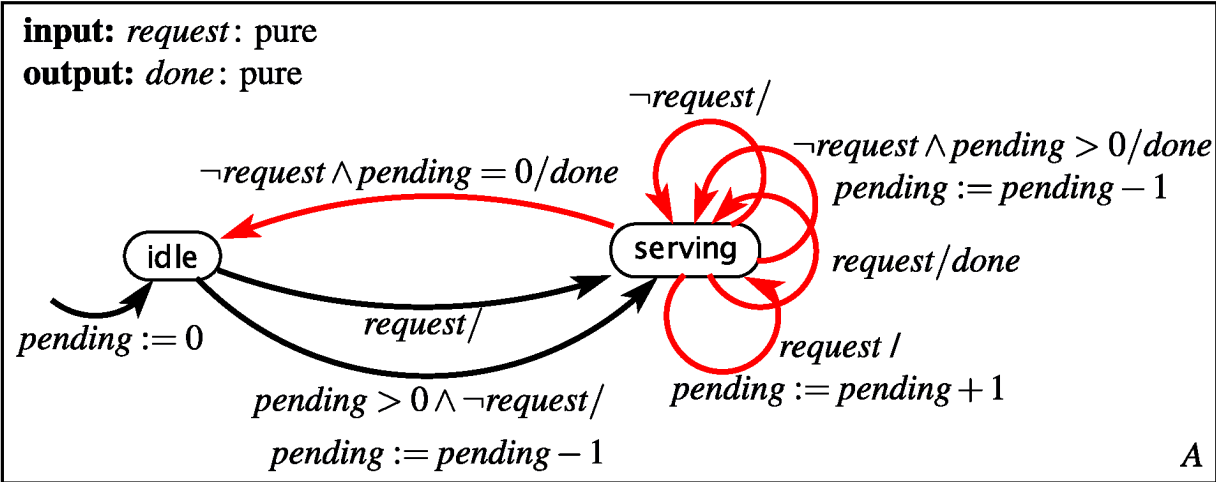
**variables:** *count*: {0, ..., 60}, *pcount*: {0, ..., 55}  
**input:** *pedestrian*: pure  
**outputs:** *sigR*, *sigG*, *sigY*, *pedR*, *pedG*: pure

Synchronous  
composition  
with  
unreachable  
states  
removed



# Shared Variables: Two Servers

**shared variable:** *pending*: int  
**input:** *request*: pure  
**outputs:** *doneA*, *doneB* : pure



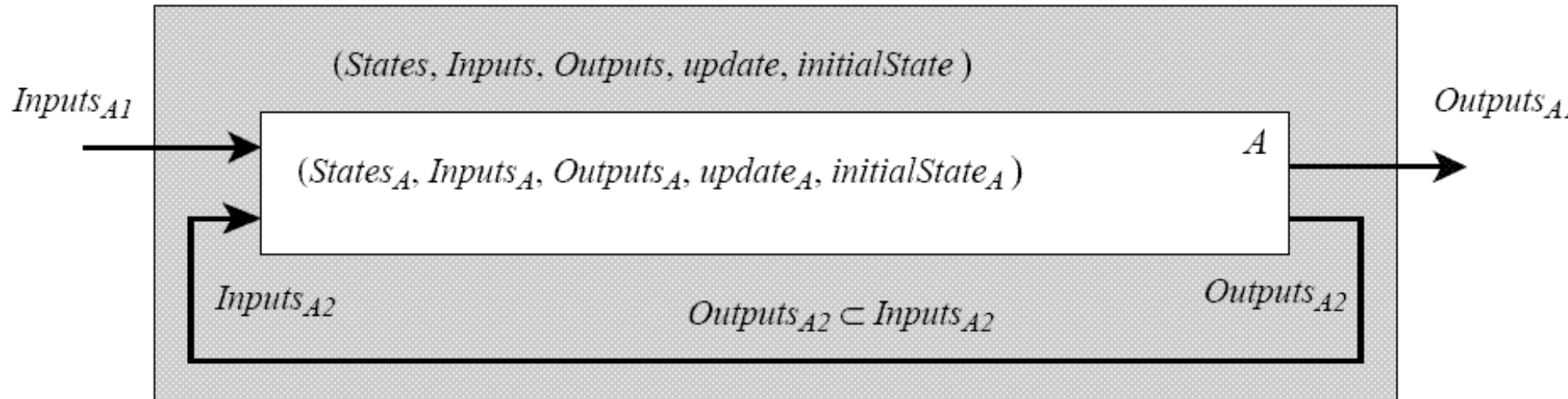
request

request

request

C

# Feedback Composition



*More on this later... Very subtle.*

# Systematic exploration of concurrent behaviors

Use hierarchy (next lecture).

Construct the product automaton using synchronous or asynchronous composition as appropriate.

Specify criteria for correctness (we will use temporal logic).

Reason using the product FSM and the correctness criteria (use systematic, algorithmic techniques).